

Online Comfort-Constrained HVAC Control via Feature Transfer

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ACM e-Energy

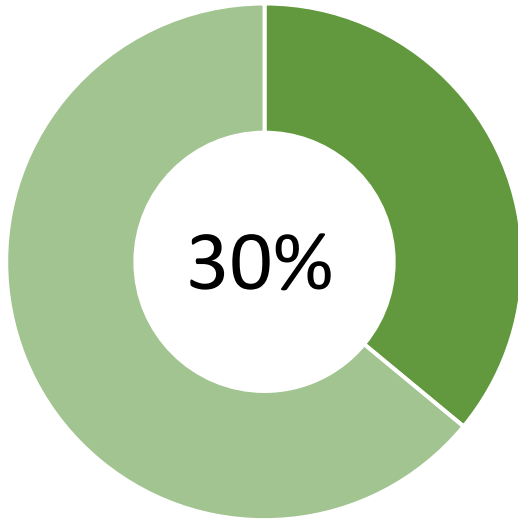
June 2025



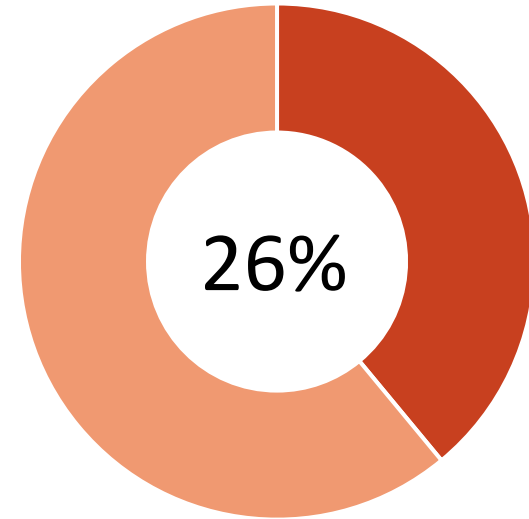
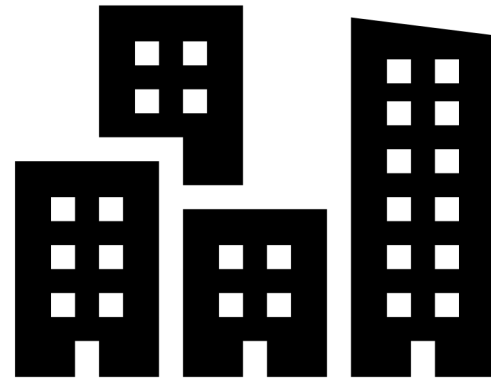
Caltech

Buildings are a Major Driver of Global Energy Use and Emissions

The operations of buildings account for



of global final energy consumption



of global energy-related carbon emissions

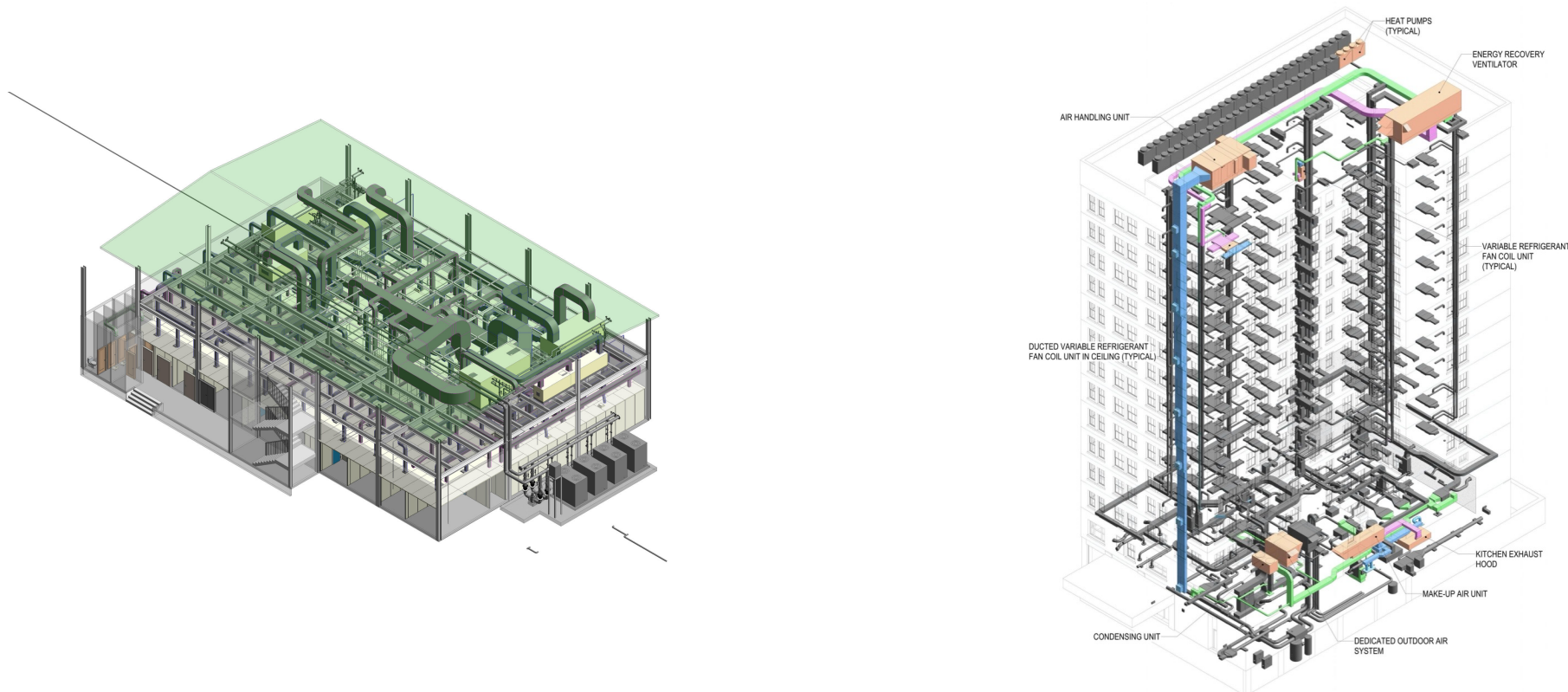
Buildings are a Major Driver of Global Energy Use and Emissions

HVAC is responsible for a significant proportion of a building's energy consumption



Learning-Based Strategies Yield Major Energy Savings

But they require extensive offline data or costly online interaction



Can we transfer and reuse a model (or a control policy) trained for a different building?

Transfer Learning for HVAC Control

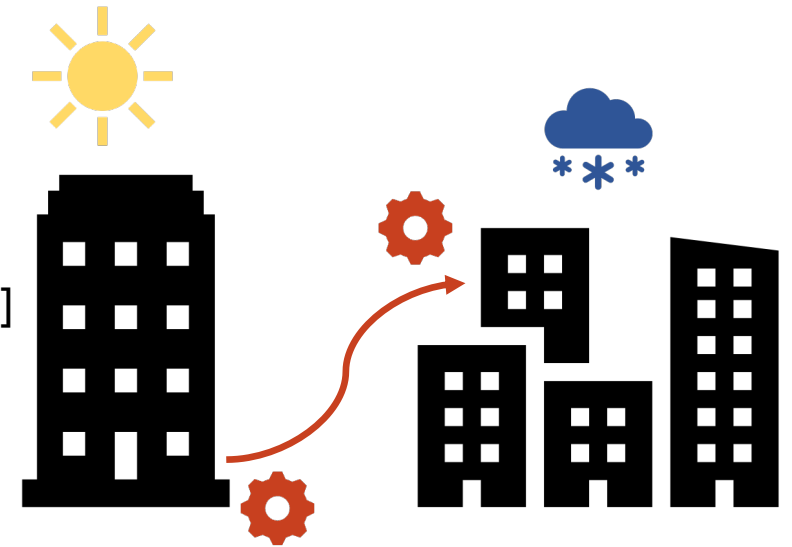
Learn relevant features from source building(s) and adapt them to target building(s)

Pros:

- Easy to **adapt** a dynamical model (or a control policy) to real-time conditions in a new building
- Significant **reduction in energy** consumption can be readily achieved [1]

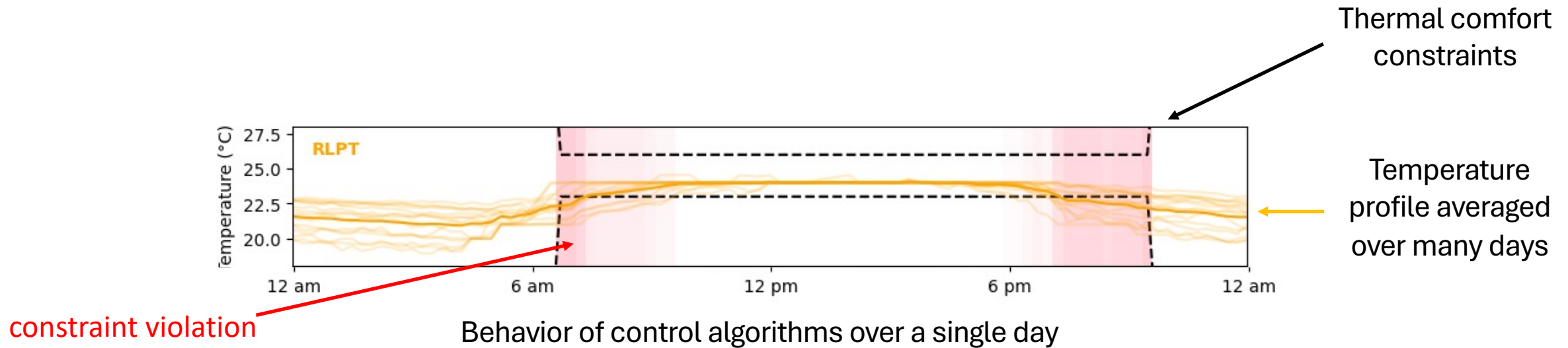
Cons:

- Requires **large and representative datasets** to build high-quality candidate system models (or candidate control policies)
- Difficult to **enforce** the new building's constraints



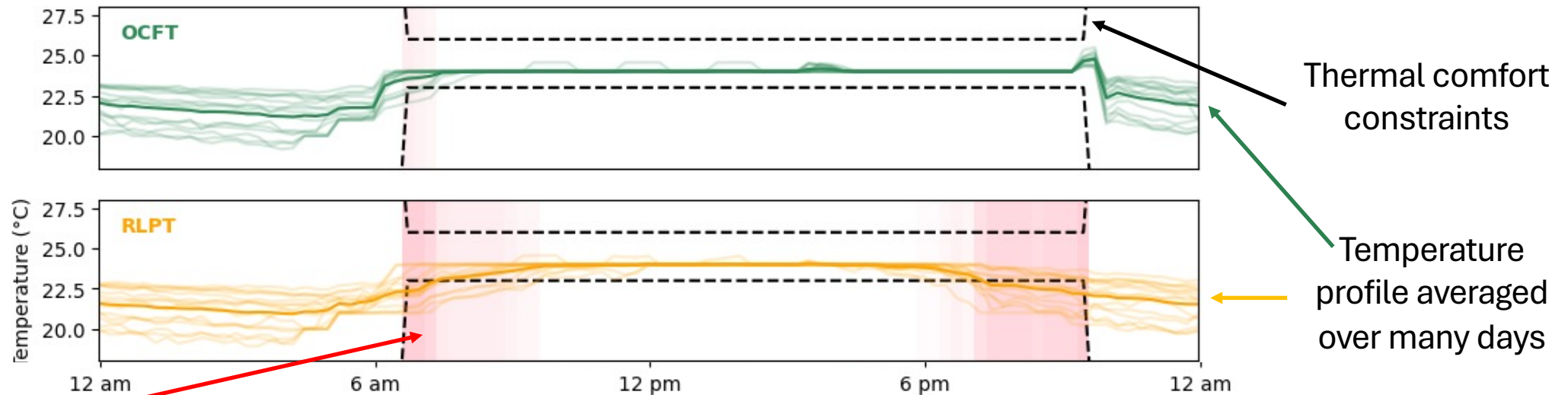
**We proposed an online
algorithm to augment a
black-box policy with safety**

A glimpse of the empirical result



A glimpse of the empirical result

Proposed method significantly reduces **constraint violation** while minimizing **energy consumption**



constraint violation

Behavior of control algorithms over a single day

OCFT: Online Comfort-Constrained HVAC Control with Feature Transfer

1. **Feature adaptation + augmentation** for transfer of **black-box** policies
 - Tunable trade-off between energy efficiency & thermal comfort violations
2. **Theoretical** insights
 - Finite constraint violations & finite-time model learning guarantees
3. **Empirical evaluations** in EnergyPlus
 - Comprehensive experiments in 19 U.S. climate zones
 - OCFT reduces constraint violations by 81.28% while using 11.23% more energy

System Model

Linear combination of nonlinear feature functions

- **State-space Representation:**

The diagram shows the equation $s_{t+1} = (\theta^*)^\top \Phi(s_t, z_t, a_t) + d_t$ with several annotations and arrows:

- An arrow from "zone temperature" points to s_t in the function Φ .
- An arrow from "system parameter" points to $(\theta^*)^\top$.
- An arrow from "features learnt in source building" points to Φ .
- An arrow from "disturbances" points to d_t .
- An arrow from "measurable states" points to s_t in the function Φ .

- **Thermal Comfort Constraints:**

$$\underline{T}_t \leq s_t \leq \overline{T}_t$$

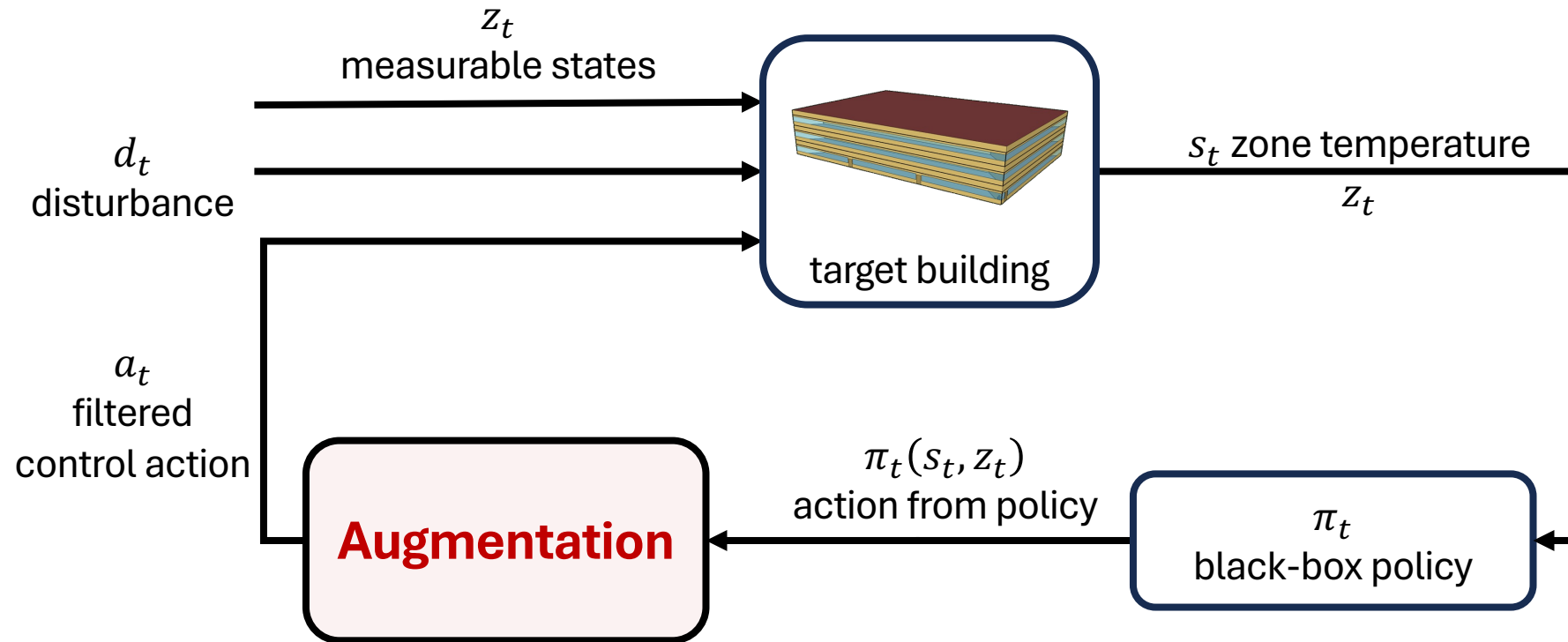
- **Exogenous Disturbances:**

$$\|d_t\|_\infty \leq W$$

Goal: **minimize energy** consumption subject to **thermal comfort constraints**

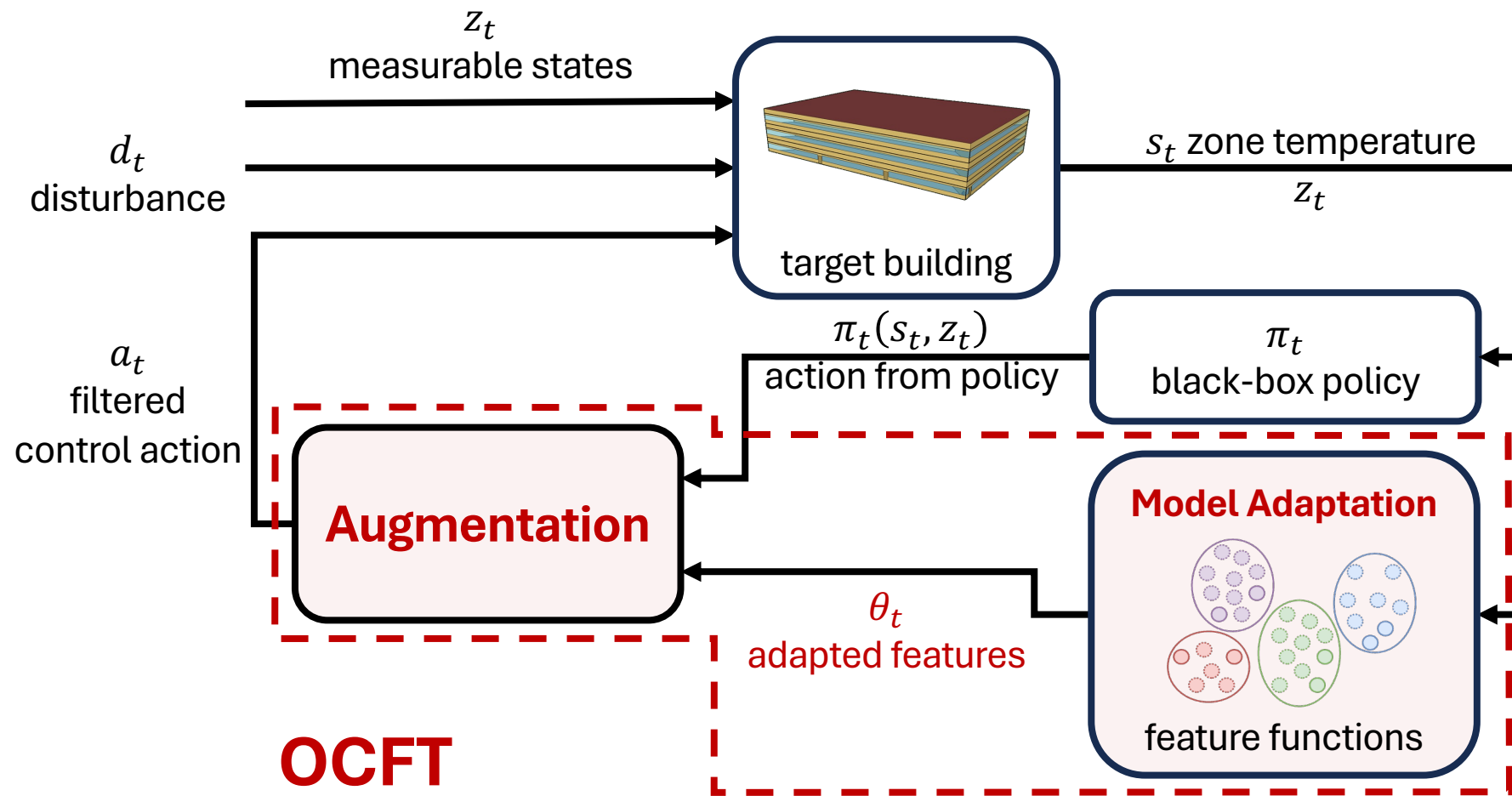
Approach

Augmentation of black-box control policy with safety



OCFT Framework

An overview



OCFT Framework

Warm start

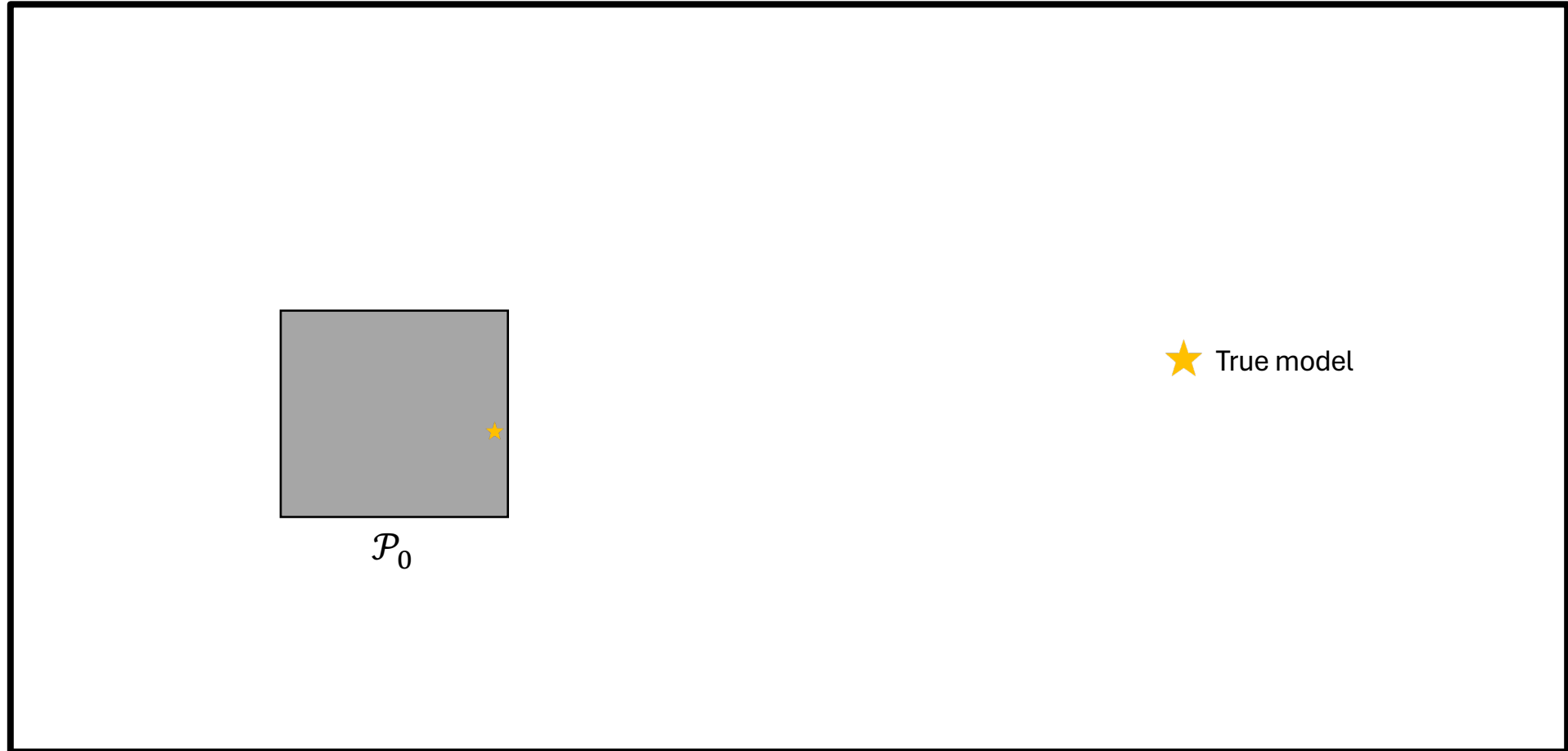
- Construct the **initial parameter uncertainty set** based on the available log data \mathcal{D} :

$$\mathcal{P}_0 = \{\theta \in \Theta: \|s_{k+1} - \theta^\top \Phi(s_k, z_k, a_k)\|_\infty \leq W, \forall (s_k, z_k, a_k) \in \mathcal{D}\}.$$

- **Log data:** 14 days of data generated under default controller in the target building
- **Interpretation:** \mathcal{P}_0 contains **all plausible models** that could have generated the log data given the disturbance bound and feature functions

OCFT Framework

Model adaptation



OCFT Framework

Model adaptation

1. Observe state transition to $s_{t+1} = (\theta^*)^\top \Phi(s_t, z_t, a_t) + d_t$



\mathcal{P}_0

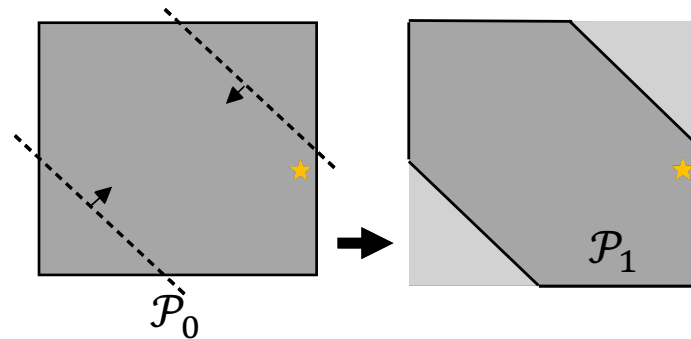
★ True model

OCFT Framework

Model adaptation

1. Observe state transition to $s_{t+1} = (\theta^*)^\top \Phi(s_t, z_t, a_t) + d_t$
2. Update the **consistent model set with new data**:

$$\mathcal{P}_t = \{\theta \in \Theta: \|s_t - \theta^\top \Phi(s_{t-1}, z_{t-1}, a_{t-1})\|_\infty \leq W\} \cap \mathcal{P}_{t-1}$$



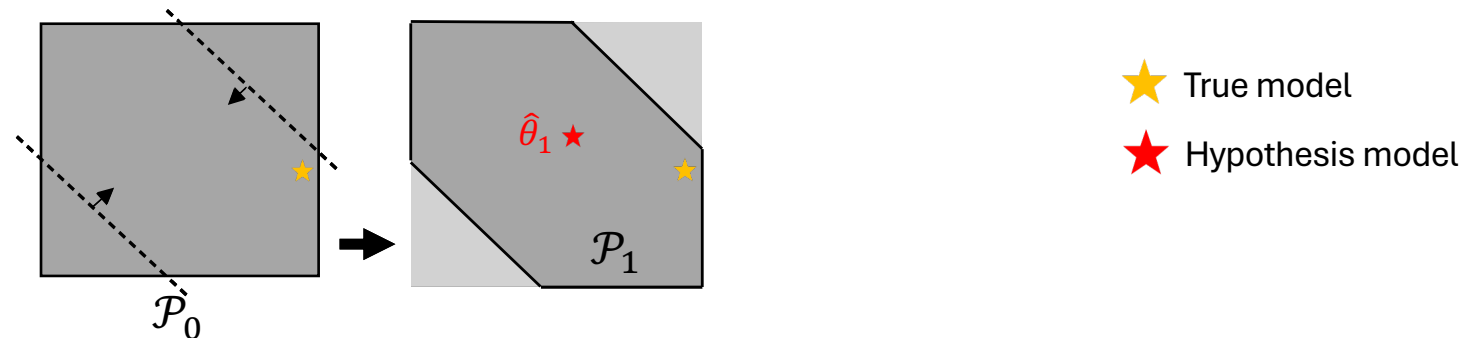
★ True model

OCFT Framework

Model adaptation

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$$\mathcal{P}_t = \{\theta \in \Theta: \|s_t - \theta^\top \Phi(s_{t-1}, z_{t-1}, a_{t-1})\|_\infty \leq W\} \cap \mathcal{P}_{t-1}$$



3. Pick a ***hypothesis model*** (potentially wrong): $\hat{\theta}_t \in \mathcal{P}_t$ using **nested convex body chasing (NCBC)**

OCFT Framework

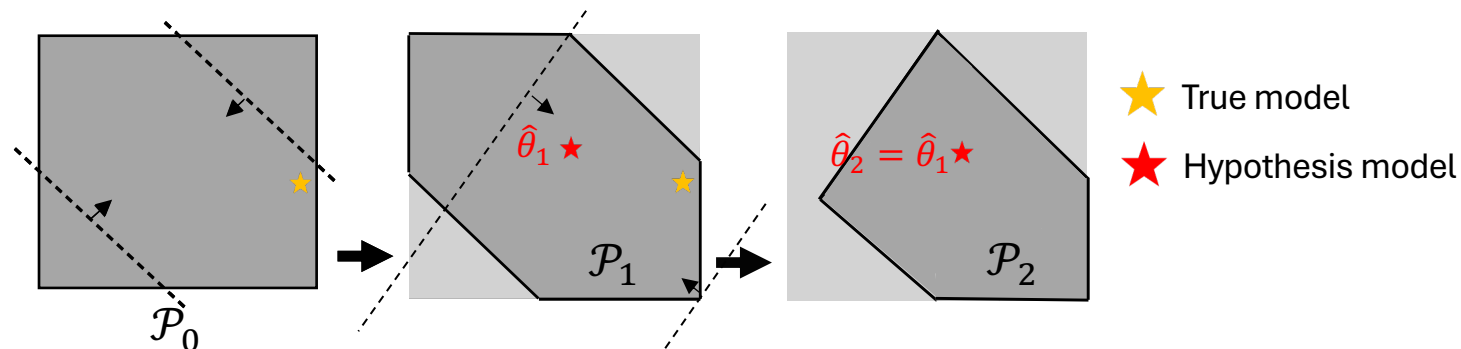
Model adaptation

$t + 1$

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3. Pick a ***hypothesis model*** (potentially wrong): $\hat{\theta}_t \in \mathcal{P}_t$ using

nested convex body chasing (NCBC)

OCFT Framework

Policy augmentation

Given black-box policy π_t , pass the suggested action through a filter based on $\hat{\theta}_t$:

trade-off parameter

adherence to black-box policy
for energy use reduction

thermal constraint violation

$$\min_{a \in \mathcal{A}, \delta_1, \delta_2 \in \mathbb{R}} \lambda \|a - \pi_t(s_t)\|_2^2 + \eta_1 |\delta_1|^2 + \eta_2 |\delta_2|^2,$$

s. t.

$$\underline{T}_t + k - \delta_1 \leq \hat{\theta}_t^\top \Phi(s_t, z_t, a) \leq \overline{T}_t - k + \delta_2,$$
$$k = W + \epsilon.$$

robust satisfaction of constraints
against worst-case disturbances

slack variables

Theoretical insights

- **Adversarial disturbances** (worst-case model mismatch between our model and the true HVAC dynamics)

Guarantee: OCFT makes finitely many thermal constraint violations

- **Stochastic disturbances** (when our model perfectly characterizes the true HVAC system dynamics)

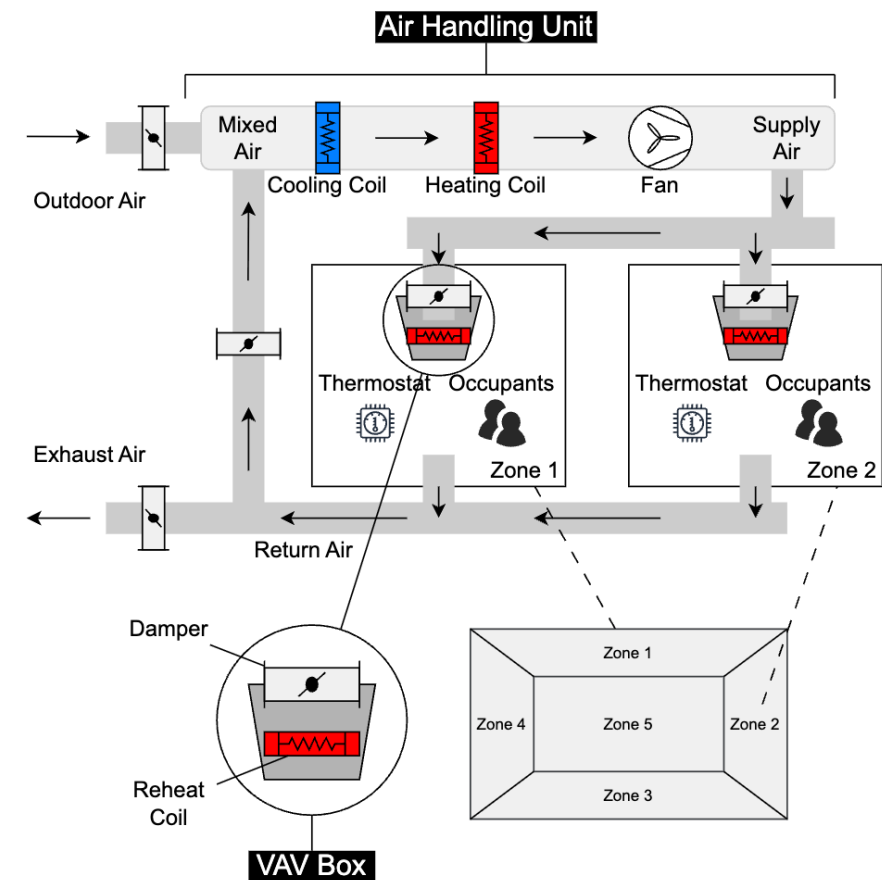
Guarantee: OCFT will learn the true system model with finite-time convergence guarantee

Experimental Results

Setup

Central AHU with zone-level VAV systems, each including a damper and a reheat coil. We control only the damper position.

- **Target building:** 15-zone medium office building in 19 climates
- **Experiment period:** January and July
- **Warm-start data:** Two weeks of historical data from target building prior to each experiment period
- **Transfer policies:** 870 RL policies trained in a 5-zone building (Climate Zone 5B, January)
- **Feature functions:** ICNNs trained across various months in Climate Zone 5B



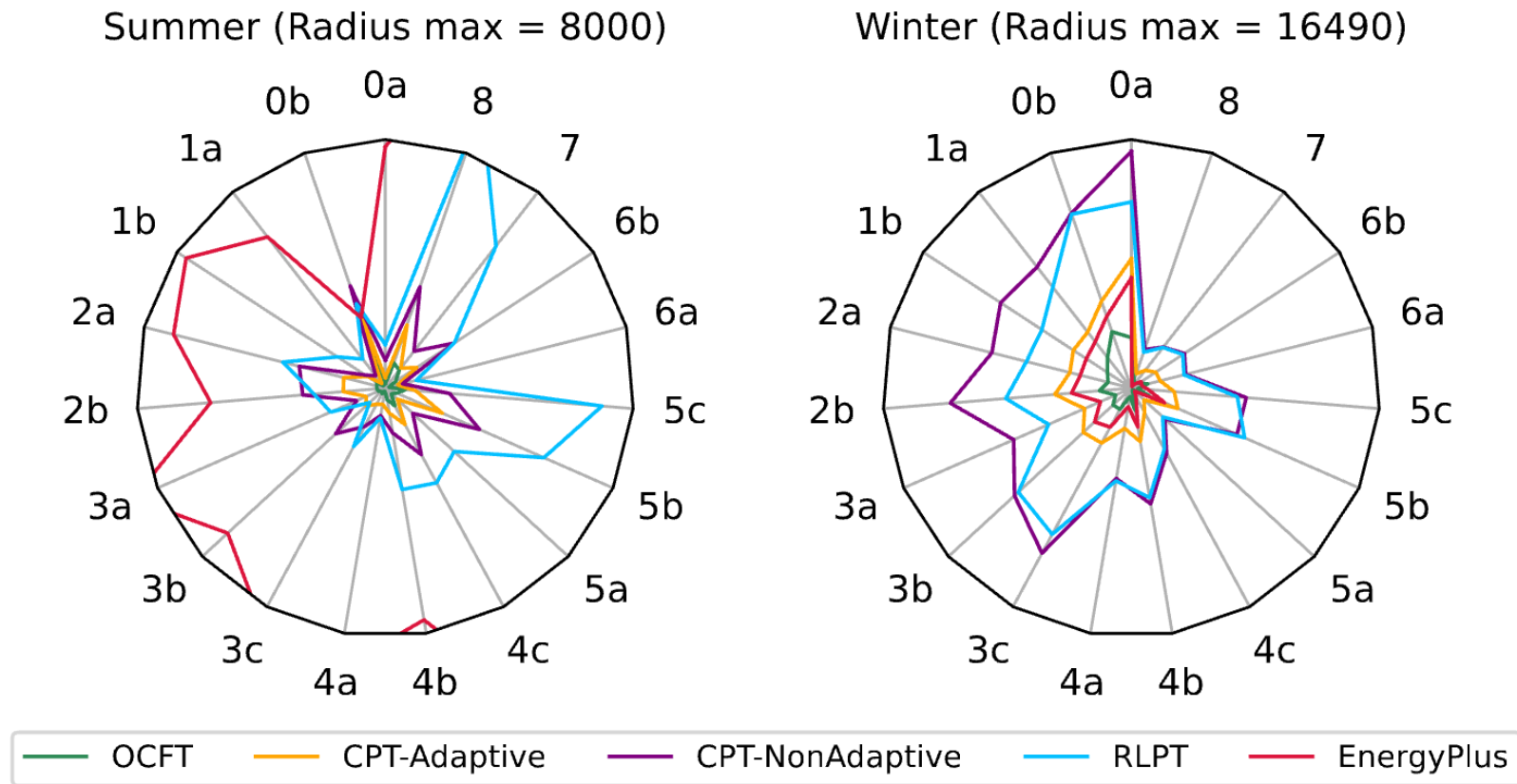
Experimental Results

Baseline algorithms

- Reinforcement Learning Policy Transfer (**RLPT**)
- Constrained Policy Transfer with Feature Function Adaptation (**CPT-Adaptive**)
 - adapted ICNN used in the projection layer for constraint satisfaction
- Constrained Policy Transfer without Feature Function Adaptation (**CPT-NonAdaptive**)
 - transferred ICNN used in the projection layer for constraint satisfaction
- Default Air System Control Strategy (**EnergyPlus**)

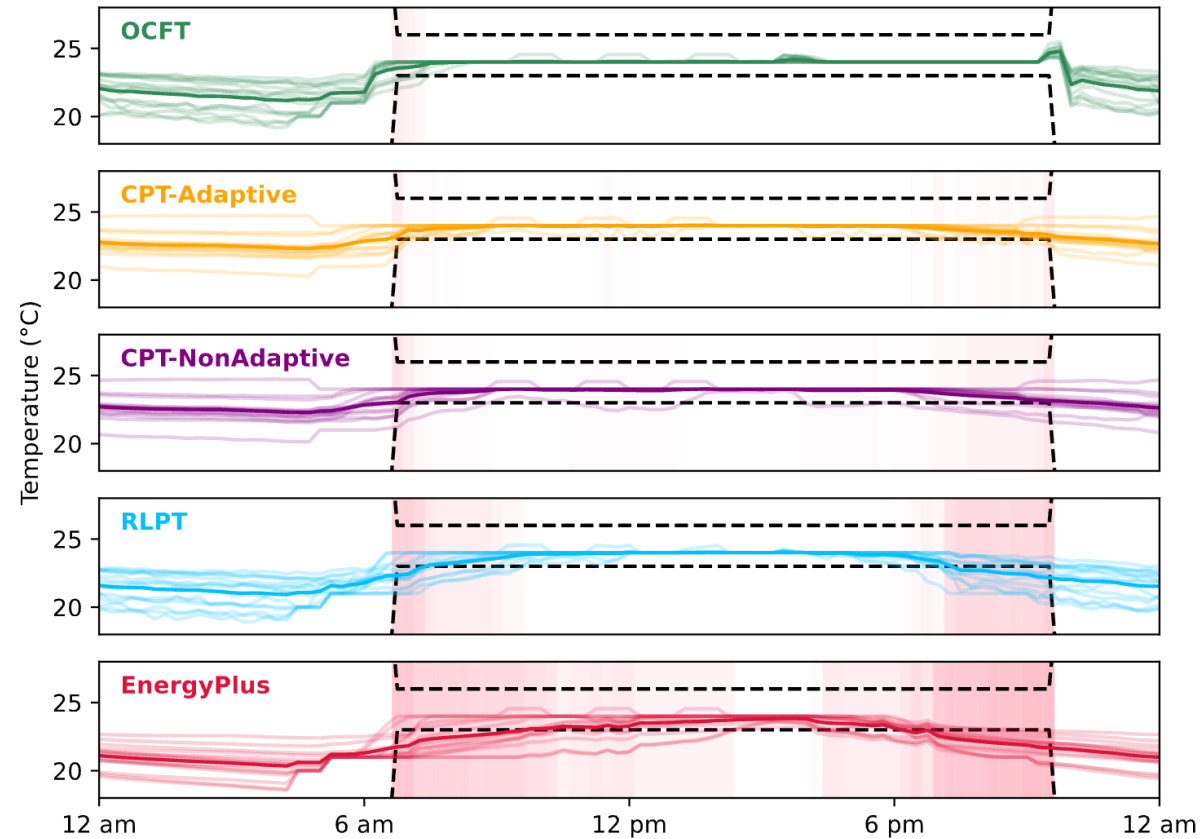
Experimental Results

Comfort constraint violations



Experimental Results

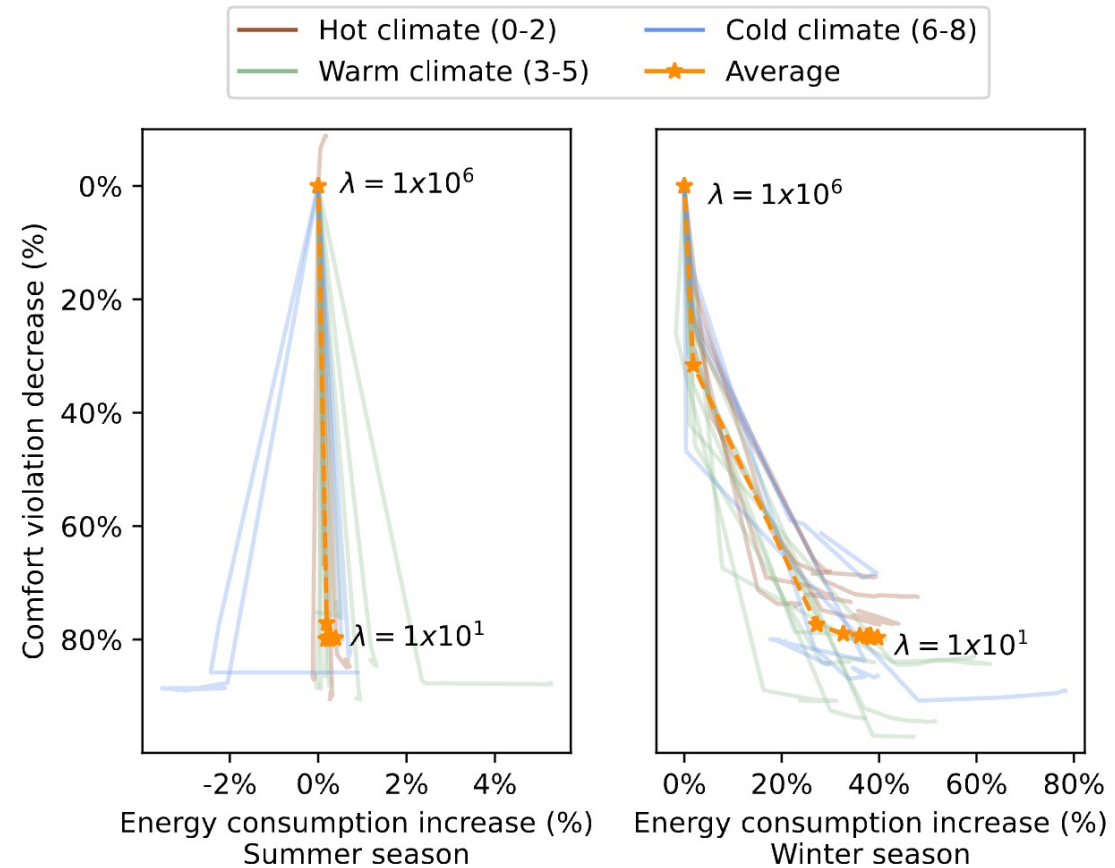
Temperature profile



Climate 5b in July

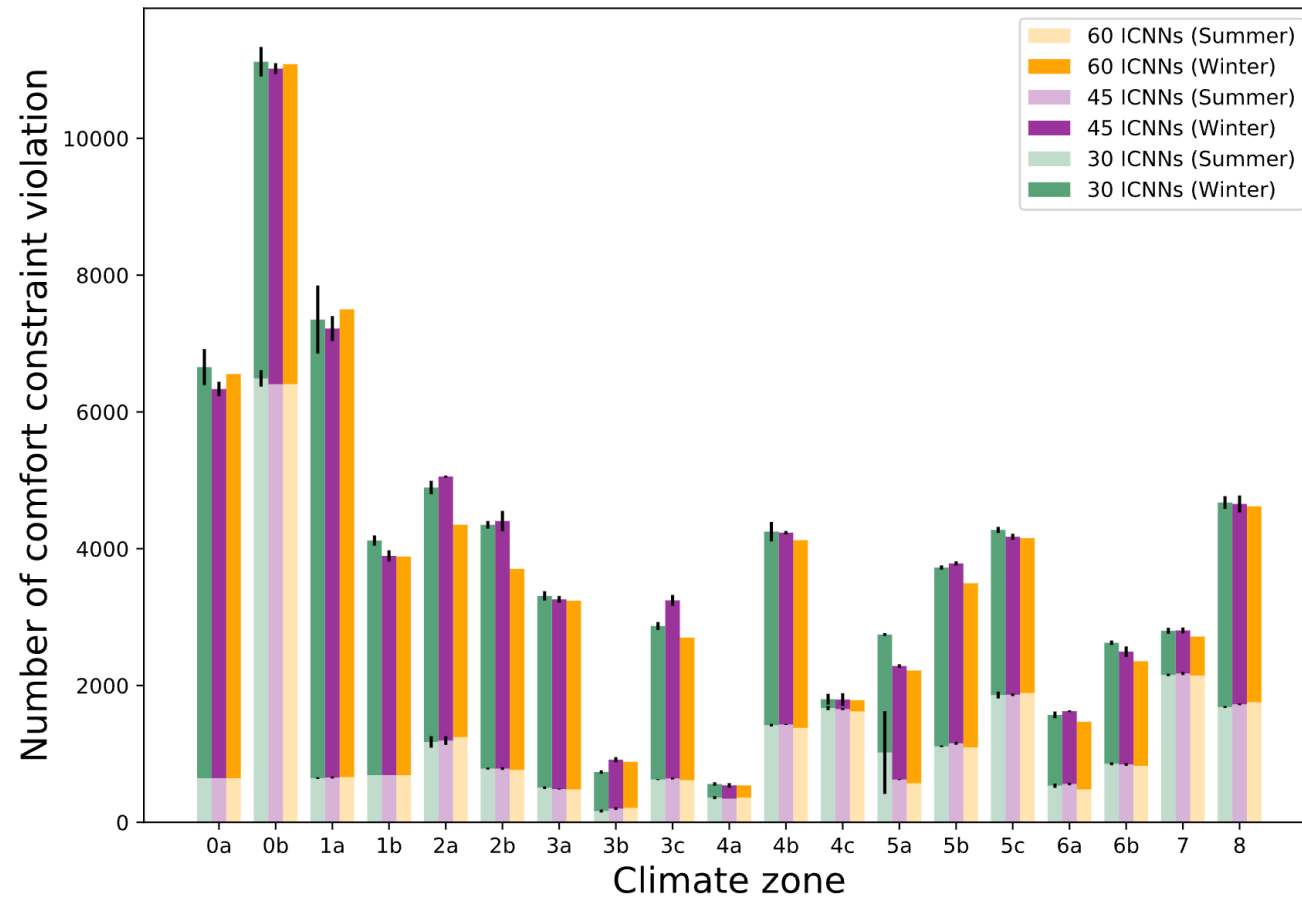
Experimental Results

Energy-comfort trade-off



Experimental Results

Robustness to feature function selection



$$s_{t+1} = (\theta^*)^\top \Phi(s_t, z_t, a_t) + d_t$$

ICNN : feature functions $\Phi(s_t, z_t, a_t)$ trained
from the source building

Takeaways

- OCFT augments black-box transfer learning algorithms
 - Robust to small and simple feature functions
 - Requires little data to warm start and minimal tuning of parameters
 - Code: github.com/sustainable-computing/ocft
- OCFT trades off energy consumption & thermal comfort constraints
 - Reduces constraint violation by 81% while using 11% extra energy (vs. most energy-efficient baseline)
 - Reduces constraint violation by 59% while using 8% extra energy (vs. least constraint-violating baseline)

