Chapter 9 FOURIER Transform Method For PDEs

The general idea of the Fourier method for real-world problems is as follows. First, we transform the given differential equation from x-domain to ω -domain, do all calculations in ω -domain, and finally use the inverse transform to represent the solution in x-domain. As we will see in the sequel, the work in ω -domain is much simpler than working in x-domain. Fig.9.1 shows that process schematically.

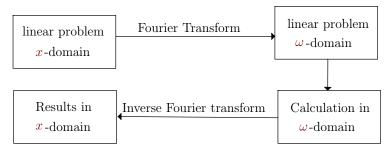


Figure 9.1.

9.1 1D problems

9.1.1 Heat problem and heat kernel

Consider the following homogeneous heat problem

$$\begin{cases} \partial_t u = \partial_{xx} u, -\infty < x < \infty, t > 0\\ u(0, x) = u_0(x) \end{cases}.$$
(9.1)

Note that there is no boundary condition for the problem. However, from the physical point of view, we pose the *boundedness condition* so that a true solution must be bounded at $|x| \to \infty$ for all t > 0. Let us first assume that the initial condition $u_0(x)$ has the FOURIER transform $\hat{u}_0(\omega)$. By taking the FOURIER transform of the problem with respect to x, we reach the following equation

$$\begin{bmatrix} \partial_t \hat{u}(t,\omega) = -\omega^2 \hat{u}(t,\omega) \\ \hat{u}(0,\omega) = \hat{u}_0(\omega) \end{bmatrix},$$
(9.2)

where $\hat{u}(t, \omega)$ is the transform of u(t, x) with respect to x. Note that the obtained problem is an ordinary equation in ω -domain which is solved for

$$\hat{u}(t,\omega) = \hat{u}_0(\omega) e^{-\omega^2 t}.$$
(9.3)

Now, the solution u(t, x) is written by the aid of inverse transform as

$$u(t,x) = \mathcal{F}^{-1}\{\hat{u}_0(\omega) e^{-\omega^2 t}\} = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{u}_0(\omega) e^{-\omega^2 t} e^{i\omega x} d\omega.$$
(9.4)

Example 9.1. Consider the following problem

$$\begin{cases} \partial_t u = \partial_{xx} u, -\infty < x < \infty, t > 0 \\ u(0, x) = \delta(x) \end{cases},$$

where $\delta(x)$ is the DIRAC delta function. The problem in ω domain reads

$$\begin{cases} \partial_t \hat{u} = -\omega^2 \, \hat{u} \\ \hat{u}_0(\omega) = 1 \end{cases},$$

that is solved for $\hat{u}(t, \omega) = e^{-\omega^2 t}$. Therefore, the solution u(t, x) is derived by the inverse transform

$$u(t,x) = \mathcal{F}^{-1}\{e^{-\omega^2 t}\} = \frac{1}{\sqrt{4\pi t}} e^{-\frac{x^2}{4t}}.$$

This is the *fundamental solution* of a simple heat equation.

Example 9.2. Let us solve the following heat problem

$$\begin{cases} \partial_t u = k \partial_{xx} u, -\infty < x < \infty, t > 0 \\ u(0, x) = e^{-|x|} \end{cases},$$

where k > 0 is a constant. Taking transform of the above equation, we reach

$$\begin{cases} \partial_t \hat{u} = -k\omega^2 \, \hat{u} \\ \hat{u}(0,\omega) = \frac{2}{1+\omega^2} \end{cases}$$

and thus

$$\hat{u}(t,\omega) = \frac{2}{1+\omega^2}e^{-k\omega^2 t}.$$

Note that \hat{u} is even, and therefore

$$u(t,x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{e^{-k\omega^2 t}}{1+\omega^2} \cos(\omega x) \, d\omega.$$

The graph of the solution is shown in Fig.9.2 for k = 1 and for t = 0, 0.1, 0.5 and t = 2.

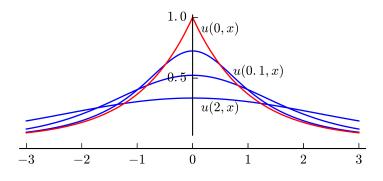


Figure 9.2.

9.1 1D problems

Remark 9.1. Observe that the solution spreads out in time and that the sharp point in the initial heat profile (at x=0) immediately disappear. In fact, the solution is averaged for t > 0. This averaging process conserves the total thermal energy of the system, and makes the solution smooth.

Example 9.3. Let us solve the following problem

$$\begin{cases} \partial_t u = \partial_{xx} u + \frac{\delta(t)}{1+x^2} \\ u(0,x) = 0 \end{cases}.$$

By the FOURIER transform of the equation, we reach the following equation

$$\begin{cases} \partial_t \hat{u} = -\omega^2 \hat{u} + \pi e^{-|\omega|} \delta(t) \\ \hat{u}(0,\omega) = 0 \end{cases}.$$

The above differential equation can be solved, for example, by the LAPLACE transform method. The solution is

$$(s+\omega^2)\hat{U}(s,\omega) = \pi e^{-|\omega|},$$

and therefore $\hat{u}(t,\omega) = \pi e^{-|\omega|} e^{-\omega^2 t}$. Thus, the solution u is

$$u(t,x) = \int_0^\infty e^{-\omega} e^{-\omega^2 t} \cos(\omega x) d\omega.$$

It is simply verified that the obtained solution is the same as the solution to the following problem

$$\begin{cases} \partial_t u = \partial_{xx} u \\ u(0,x) = \frac{1}{1+x^2} \end{cases}$$

9.1.2 Convolution representation of the solution

Back to formula (9.3), we can use the convolution formula and write the solution to a heat equation as follows

$$\mathcal{F}^{-1}\{\hat{u}_0(\omega)\,e^{-\omega^2 t}\} = u_0(x) * \mathcal{F}^{-1}\{e^{-\omega^2 t}\} = u_0(x) * \frac{1}{\sqrt{4\pi t}}e^{-\frac{x^2}{4t}}$$

The function $\Phi(t, x) = \frac{1}{\sqrt{4\pi t}} e^{-\frac{x^2}{4t}}$ is called the fundamental solution of the heat equation or the *heat kernell*. Therefore,

$$u(t,x) = \int_{\mathbb{R}} u_0(y) \Phi(t,x-y) \, dy = \frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} u_0(y) \, e^{-\frac{(x-y)^2}{4t}} \, dy. \tag{9.5}$$

Formulation presented in (9.5) has an advantage over (9.4). In fact, one can use (9.4) only when $u_0(x)$ has a FOURIER transform.

Example 9.4. Let us solve the following heat problem

$$\begin{cases} \partial_t u = \partial_{xx} u, -\infty < x < \infty, t > 0 \\ u(0, x) = \begin{cases} 1 & x < 0 \\ 2 & x > 0 \end{cases} \end{cases}$$

The relation (9.5) gives the solution

$$\begin{split} u(t,x) &= \frac{1}{\sqrt{4\pi t}} \int_{-\infty}^{0} e^{-\frac{(x-y)^2}{4t}} dy + \frac{2}{\sqrt{4\pi t}} \int_{0}^{\infty} e^{-\frac{(x-y)^2}{4t}} dy.\\ &\frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} e^{-\frac{y^2}{4t}} dy = 1, \end{split}$$

and thus, at x = 0 we obtain $u(t, 0) = \frac{3}{2}$. Fig.9.3 shows the solution for t = 0.01, 0.05, 0.2. As it is observed from the figure, the solution becomes smooth immediately for t > 0.

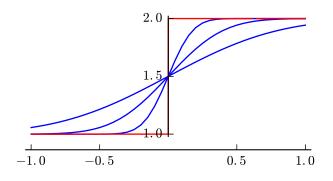


Figure 9.3.

9.1.3 Heat problems in semi-infinite domain

Consider a heat problem defined on the semi-infinite domain $x \in (0, \infty)$

$$\begin{cases} \partial_t u = \partial_{xx} u, 0 < x < \infty, t > 0 \\ u(t, 0) = 0 \\ u(0, x) = f(x) \end{cases}$$
(9.6)

Because the domain of x is defined in $(0, \infty)$, we should use the sine or cosine FOURIER integrals. According to the given boundary condition, we choose the sine FOURIER transform for the problem and write

$$\begin{cases} \partial_t \hat{u}_s(\omega) = -\omega^2 \, \hat{u}_s(\omega) \\ \hat{u}_s(0,\omega) = \hat{f}_s(\omega) \end{cases}.$$

THe solution $\hat{u}_s(t,\omega)$ is

$$\hat{u}_s(t,\omega) = \hat{f}_s(\omega) e^{-\omega^2 t},$$

and thus

$$u(t,x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \hat{f}_s(\omega) e^{-\omega^2 t} \sin(\omega x) d\omega.$$

Notice that

9.1 1D problems

Note that u(t, 0) = 0 for all $t \ge 0$.

Example 9.5. Let us solve the following heat problem

$$\begin{cases} \partial_t u = \partial_{xx} u + t f(x), 0 < x < \infty, t > 0 \\ u(t, 0) = 0 \\ u(0, x) = 0 \end{cases},$$

where f(x) = 1 for 0 < x < 1 and zero otherwise. Let us take the sine FOURIER transform of the problem and rewrite the equation as follows

$$\begin{cases} \partial_t \hat{u}_s(t,\omega) = -\omega^2 \hat{u}_s(t,\omega) + t \frac{1 - \cos\omega}{\omega} \\ \hat{u}_s(0,\omega) = 0 \end{cases}$$

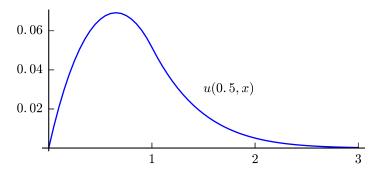
The above problem is solved for

$$\hat{u}_s(t,\omega) = \frac{1 - \cos\omega}{\omega} e^{-\omega^2 t} \int_0^t s \, e^{\omega^2 s} \, ds = \frac{1 - \cos\omega}{\omega} \Biggl\{ \frac{t}{\omega^2} - \frac{1 - e^{-\omega^2 t}}{\omega^4} \Biggr\}.$$

The solution u(t, x) is derived then by the following formula

$$u(t,x) = \frac{2}{\pi} \int_0^\infty \hat{u}_s(t,\omega) \sin(\omega x) \, d\omega.$$

Fig.9.4 shows the solution for t = 0.5.





Remark 9.2. If the boundary condition is $\partial_x u(t, 0) = 0$, we choose the cosine FOURIER transform for the problem.

9.1.4 Wave problem and d'Alembert formula

The method to solve a wave equation is completely similar to solve a heat problem. Consider the following equation

$$\begin{cases} \partial_{tt} u = c^2 \partial_{xx} u, -\infty < x < \infty \\ u(0, x) = f(x) \\ \partial_t u(0, x) = g(x) \end{cases}.$$

Let us write the solution as follows

$$u(t,x) = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{u}(t,\omega) e^{i\omega x} d\omega,$$

for an undetermined function $\hat{u}(t, \omega)$. To determine \hat{u} , we substitute the integral into the equation and obtain

$$\begin{cases} \partial_{tt} \hat{u}(t,\omega) = -c^2 \omega^2 \hat{u}(t,\omega) \\ \hat{u}(0,\omega) = \hat{f}(\omega), \partial_t \hat{u}(0,\omega) = \hat{g}(\omega) \end{cases}.$$

The general solution to the above initial value problem is

$$\hat{u}(t,\omega) = \hat{f}(\omega)\cos(c\omega t) + \frac{1}{c\omega}\hat{g}(\omega)\sin(c\omega t),$$

and thus

$$u(t,x) = \mathcal{F}^{-1}\{\hat{f}(\omega)\cos(c\omega t)\} + \frac{1}{c}\mathcal{F}^{-1}\left\{\frac{1}{\omega}\hat{g}(\omega)\sin(c\omega t)\right\}.$$

According to the convolution formula, one can write

$$\mathcal{F}^{-1}\{\hat{f}(\omega)\cos(c\omega t)\} = f(x) * \frac{1}{2}[\delta(x-ct) + \delta(x+ct)] = \frac{1}{2}[f(x-ct) + f(x+ct)].$$

For the second term, we have

$$\frac{1}{c}\mathcal{F}^{-1}\left\{\frac{1}{\omega}\hat{g}(\omega)\sin(c\omega t)\right\} = \frac{-1}{2c}\left(\int_0^x g(s)ds\right) * \left[\delta(x-ct) - \delta(x+ct)\right] = \frac{1}{2c}\int_{x-ct}^{x+ct} g(s)ds.$$

Therefore, the solution can be written as

$$u(t,x) = \frac{1}{2} [f(x-ct) + f(x+ct)] + \frac{1}{2c} \int_{x-ct}^{x+ct} g(s) ds.$$
(9.7)

.

Example 9.6. Let us solve the following damped wave equation

$$\begin{cases} \partial_{tt}u + 2\xi \partial_t u = c^2 \partial_{xx} u \\ u(0, x) = f(x) \\ \partial_t u(0, x) = g(x) \end{cases}$$

By the FOURIER transform, the problem reduces to

$$\left\{ \begin{array}{l} \partial_{tt} \hat{u} + 2\xi \partial_t \hat{u} = -c^2 \omega^2 \hat{u} \\ \hat{u}(0,\omega) = \hat{f}(\omega), \partial_t \hat{u}(0,\omega) = \hat{g}(\omega) \end{array} \right. .$$

For example, if g = 0 then the solution is

$$\hat{u}(t,\omega) = e^{-\xi t} \hat{f}(\omega) \bigg[\cos(\mu t) + \frac{\xi}{\mu} \sin(\mu t) \bigg],$$

where $\mu = \sqrt{\omega^2 - \xi^2}$. The figure (9.5) shows the solution u(t, x) when c = 1 and $\xi = 0.5$ if $f(x) = \begin{cases} (1-x^2)/4 & -1 \le x \le 1 \\ 0 & \text{othersise} \end{cases}$. Observe that two branches are not separated completely due to the damping factor ξ .

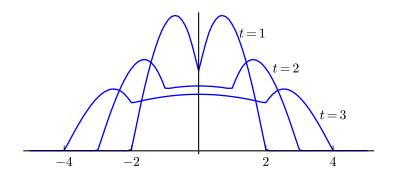


Figure 9.5.

9.1.5 Heat kernel

Consider the following heat problem

$$\begin{cases} \partial_t u = \partial_{xx} u, -\infty < x < \infty, t > 0 \\ u(0, x) = \delta(x - x_0) \end{cases},$$

where x_0 is an arbitrary point in $(-\infty, \infty)$, and δ is the DIRAC delta function. According to relation (9.5), the solution can be written as

$$u(t,x) = \frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} \delta(y-x_0) \, e^{-\frac{(x-y)^2}{4t}} \, dy = \frac{1}{\sqrt{4\pi t}} e^{-\frac{(x-x_0)^2}{4t}},$$

and thus the fundamental solution $\Phi(t, x)$ is called sometime the *impulse response* of the heat equation. Accordingly, the response to an arbitrary initial heat profile can be written as

$$u(t,x) = u_0(x) * \Phi(t,x).$$

As it is observe from Fig.9.6, the solution shrinks at x_0 for $t \rightarrow 0$.

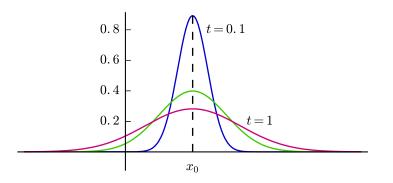


Figure 9.6.

The following proposition states that the initial thermal energy (if it is finite) is conserved for t > 0.

Proposition 9.1. Assume that the initial heat profile $u_0(x)$ in (9.1) is integrable. Then the solution decay in long term

$$\lim_{t \to \infty} u(t, x) = 0, \tag{9.8}$$

and furthermore

$$\int_{\mathbb{R}} u(t,x) \,\mathrm{d}x = \int_{\mathbb{R}} u_0(x) \,\mathrm{d}x. \tag{9.9}$$

Proof. We have

$$\lim_{t \to \infty} u(t, x) = \lim_{t \to \infty} \int_{\mathbb{R}} u_0(y) \Phi(t, x - y) \, dy = \int_{\mathbb{R}} u_0(y) \lim_{t \to \infty} \Phi(t, x - y) \, dy.$$

The limit can be passed inside the integral according to the dominant convergence theorem. Note that

$$|u_0(y)\Phi(t, x-y)| < |u_0(y)|,$$

and $u_0(x)$ is integrable. On the other hand, since we have

$$\lim_{t\to\infty}\Phi(t,x-y)=0,$$

we conclude (9.8). To show (9.9), we take x - y = z and write

$$\int_{\mathbb{R}} u(t,x) \, \mathrm{d}x = \int_{\mathbb{R}} \int_{\mathbb{R}} u_0(y) \Phi(t,x-y) \, \mathrm{d}y = \int_{\mathbb{R}} \Phi(t,z) \left(\int_{\mathbb{R}} u_0(x-z) \, dx \right) \, \mathrm{d}z.$$

Since u_0 is integrable, we have

$$\int_{\mathbb{R}} u_0(x-z) \, dx = \int_{\mathbb{R}} u_0(x) \, \mathrm{d}x,$$

and therefore

$$\int_{\mathbb{R}} u(t,x) \, \mathrm{d}x = \left(\int_{\mathbb{R}} u_0(x) \, \mathrm{d}x \right) \left(\int_{\mathbb{R}} \Phi(t,z) \, \mathrm{d}z \right)$$

It is simply verified that

$$\int_{\mathbb{R}} \Phi(t, x) dx = 1,$$

and hence (9.9).

Remark 9.3. Note that in general we can pass the limit inside the integrals and write

$$\lim_{t \to \infty} \int_{\mathbb{R}} u(t, x) \, dx = \int_{\mathbb{R}^{t \to \infty}} u(t, x) \, dx.$$

In fact, if the relation holds, by property $\lim_{t\to\infty} u(t,x) = 0$, we should have

and

which is evidently wrong. Another example is Φ itself as

$$\lim_{t \to \infty} \int_{\mathbb{R}} \Phi(t, x) \, \mathrm{d}x = \lim_{t \to \infty} 1 = 1,$$
$$\int_{\mathbb{R}} \lim_{t \to \infty} \Phi(t, x) \, \mathrm{d}x = 0.$$

Proposition 9.2. Assume that f(x) is a bounded continuous function in \mathbb{R} , then

$$\lim_{t \to 0} \frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} f(y) \, e^{-\frac{(x-y)^2}{4t}} \, dy = f(x).$$

Proof. Let $y = 2\sqrt{t} z + x$ and then

$$\frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} f(y) \, e^{-\frac{(x-y)^2}{4t}} \, dy = \frac{1}{\sqrt{\pi}} \int_{\mathbb{R}} f(2\sqrt{t} \, z+x) \, e^{-z^2} \, dz.$$

According to the dominant convergence theorem, we can write

$$\lim_{t \to 0} \frac{1}{\sqrt{4\pi t}} \int_{\mathbb{R}} f(y) e^{-\frac{(x-y)^2}{4t}} dy = \frac{1}{\sqrt{\pi}} \int_{\mathbb{R}} \lim_{t \to 0} f(2\sqrt{t}y + x) e^{-z^2} dz$$
$$= \frac{1}{\sqrt{\pi}} \int_{\mathbb{R}} f(x) e^{-\frac{z^2}{4t}} dz = \frac{f(x)}{\sqrt{\pi}} \int_{\mathbb{R}} e^{-\frac{z^2}{4t}} dz = f(x),$$

and this completes the proof.

Problem 9.1. Assume u_0 is an admissible functions, and u(t, x) is the solution to the following problem

Show the following relation
$$\begin{cases} \partial_t u = \partial_{xx} u \\ u(0, x) = u_0(x) \end{cases}$$
$$\lim_{t \to 0} u(t, x) = u_0(x)$$

Now, we use the relation (9.5) to show that u(t, x) is smooth even if the initial data is discontinuous. The proof of the following theorem is given in the appendix to this chapter.

Theorem 9.1. Assume that the initial data $u_0(x)$ is admissible, then u(t,x) given in (9.5) is smooth for t > 0.

Proof. We show that u is continuous. Fix (t, x), t > 0 and let (t_n, x_n) , $t_n > 0$ be an arbitrary sequence converging (t, x). We have

$$\lim_{n \to \infty} u(t_n, x_n) = \lim_{n \to \infty} \int_{\mathbb{R}} u_0(y) \Phi(t_n, x_n - y) dy.$$

Since $t_n > 0$, $t_n \to t$, and t > 0, without loss of generality, we can assume that $t_n > \varepsilon$ for some $\varepsilon > 0$ and for all n. On the other hand, for any $\varepsilon > 0$ there is M > 0 such that $\Phi(t_n, x - y) < M$ regardless of x, y. In fact, we have

$$\Phi(t_n, x - y) = \frac{1}{\sqrt{4\pi t_n}} e^{-\frac{(x - y)^2}{4t_n}} \le \frac{1}{\sqrt{4\pi t_n}} < \frac{1}{\sqrt{4\pi\varepsilon}} = M.$$

Therefore

$$|u_0(y)\Phi(t_n, x_n - y)| < M |u_0(y)|.$$

Since f in integrable, we use the dominant convergence theorem and write

$$\lim_{n \to \infty} u(t_n, x_n) = \int_{\mathbb{R}} u_0(y) \lim_{n \to \infty} \Phi(t_n, x_n - y) dy = \int_{\mathbb{R}} u_0(y) \Phi(t, x - y) dy = u(t, x).$$

Hence, the continuity is proved. Let us show that u(t, x) is continuously differentiable with respect to t for t > 0. Fix t and let h be small enough such that t + h > 0. We have

$$\frac{u(t+h,x) - u(t,x)}{h} = \int_{\mathbb{R}} u_0(y) \frac{\Phi(t+h,x-y) - \Phi(t,x-y)}{h} \, dy.$$

 $\Phi(t, x)$ is smooth for t > 0, and thus there is M = M(t) such that

$$|\partial_t \Phi(t,x)| < M$$

Therefore, we have

$$\lim_{h \to 0} \frac{u(t+h,x) - u(t,x)}{h} = \int_{\mathbb{R}} u_0(y) \lim_{h \to 0} \frac{\Phi(t+h,x-y) - \Phi(t,x-y)}{h} \, \mathrm{dy} = \int_{\mathbb{R}} u_0(y) \partial_t \Phi(t,x-y) \, \mathrm{dy}.$$

The differentiability of higher orders with respect to t and x is proved by a similar argument.

Problems

Problem 9.2. Solve the following heat problem in $(-\infty, \infty)$ and draw the temperature at x = 1 with respect to time

$$\begin{bmatrix} \partial_t u = \partial_{xx} u, \\ u(0, x) = e^{-x^2} \end{bmatrix}$$

Problem 9.3. Solve the following damped wave equation on $-\infty < x < \infty$

$$\begin{cases} \partial_{tt}u + 2\xi \partial_t u = \partial_{xx} u \\ u(0,x) = 0, \partial_t u(0,x) = e^{-|x|} \end{cases},$$

where $\xi > 0$ is a constant.

Problem 9.4. Solve the following heat problem on $0 < x < \infty$

$$\begin{cases} \partial_t u = k \partial_{xx} u \\ u(t,0) = 0 \\ u(0,x) = \frac{1}{1+x^2} \end{cases}$$

where k > 0 is a constant.

Problem 9.5. Solve the following heat problem

$$\begin{cases} \partial_t u = \partial_{xx} u + e^{-|x|} \\ u(0,x) = 0 \end{cases},$$

and draw the solution for t = 1.

Problem 9.6. Solve the following heat problem

$$\partial_t u = \partial_{xx} u + \frac{e^{-|x|}}{1+x^2},$$
$$u(0,x) = 0$$

and draw the solution for t = 1.

Problem 9.7. If f(x) is admissible function, show that following problems have same solution

$$\begin{cases} \partial_t u = \partial_{xx} u + \delta(t) f(x) \\ u(0,x) = 0 \end{cases}, \begin{cases} \partial_t u = \partial_{xx} u \\ u(0,x) = f(x) \end{cases}.$$

Problem 9.8. Solve the following heat problem in the domain $(-\infty, \infty)$

$$\begin{cases} \partial_t u = \partial_{xx} u \\ u(0,x) = \begin{cases} 0 & x < 0 \\ 1 & x > 0 \end{cases} \end{cases}$$

Problem 9.9. Solve the following heat equation on the domain $(0, \infty)$

$$\begin{cases} \partial_t u = \partial_{xx} u \\ \partial_x u(t,0) = 0 \\ u(0,x) = e^{-x} \end{cases}$$

Problem 9.10. Solve the following wave equation in the domain $(0, \infty)$

.

$$\begin{cases} \partial_{tt}u = 4\partial_{xx}u\\ u(t,0) = 0\\ u(0,x) = 0, \partial_t u(0,x) = e^{-\frac{x^2}{2}}. \end{cases}$$

Problem 9.11. Assume that the initial data f(x) in (9.1) is admissible.

a) Directly differentiate $\Phi(t, x)$ and verify

$$\partial_t \Phi(t, x) = \partial_{xx} \Phi(t, x).$$

b) Us the result in part (a) to show that the integral solution (9.5) is a true solution to the problem (9.1).

Problem 9.12. Draw the solution of the problem

$$\left\{ \begin{array}{l} \partial_{tt} u = \partial_{xx} u \\ u(0,x) = \left\{ \begin{array}{l} \frac{(1-x^2)}{4} & -1 \leq x \leq 1 \\ 0 & \text{othersise} \end{array} \right. , \\ \partial_t u(0,x) = 0 \end{array} \right.$$

at times t = 0.5, 1, 1.5, 2.

Problem 9.13. Solve the following wave problem and draw the solution for different instance of time

$$\begin{cases} \partial_{tt}u = \partial_{xx}u \\ u(0,x) = \delta(t-1)e^{-x^2/2} \\ \partial_t u(0,x) = 0 \end{cases}$$

Problem 9.14. Show that the solution to the problem

$$\begin{cases} \partial_t u = \partial_{xx} u & x \in (0, \infty) \\ \partial_x u(t, 0) = 0 & , \\ u(0, x) = f(x) & x \in (0, \infty) \end{cases}$$

is

$$u(t,x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \hat{f}_c(\omega) e^{\omega^2 t} \cos(\omega x) d\omega,$$

where $F_c(\omega)$ is the cosine FOURIER transform of f(x).

Problem 9.15. Solve the following problem

$$\begin{cases} \partial_t u = \partial_{xx} u & x \in (0, \infty) \\ u(t, 0) = 1 & \\ u(0, x) = \frac{1}{1 + x^2} & x \in (0, \infty) \end{cases}.$$

Problem 9.16. Even though we have the formula (9.9), use the PLANCHEREL theorem and (9.3) to show

$$\lim_{t \to \infty} \int_{-\infty}^{\infty} |u(t,x)|^2 dx = 0.$$

9.2 Higher dimensional problems

9.2.1 Laplace equation

We solve the LAPLACE equation $\Delta u = 0$ on semi-bounded domains.

LAPLACE equation on a half-plane

Consider the following problem defined on $\Omega = \{(x, y), y \ge 0\}$

$$\begin{cases} \Delta u = 0\\ u(x,0) = f(x) \end{cases}.$$

We look for solutions that remain bounded in Ω , that is,

$$\sup_{(x,y)\in\Omega} |u(x,y)| < \infty.$$
(9.10)

The above problem is equivalent to the following one in ω -domain

$$\begin{cases} \partial_{yy}\hat{u}(\omega, y) - \omega^2 \,\hat{u}(\omega, y) = 0\\ \hat{u}(\omega, 0) = \hat{f}(\omega) \end{cases}$$

Therefore, $\hat{u}(\omega, y)$ is

$$\hat{u}(\omega, y) = A(\omega) e^{\omega y} + B(\omega) e^{-\omega y},$$

for some undetermined coefficients functions $A(\omega)$, $B(\omega)$. To determine these coefficients, we apply the boundedness condition. The coefficient $A(\omega)$ must be zero for $\omega > 0$, otherwise the solution goes unbounded for $y \to \infty$. Similarly, $B(\omega)$ must be zero for $\omega < 0$. Hence, \hat{u} has the following form

$$\hat{u}(\omega, y) = \left\{ \begin{array}{ll} B(\omega) \, e^{-\omega y} & \omega > 0 \\ A(\omega) \, e^{\omega y} & \omega < 0 \end{array} \right.$$

This is equivalent to $\hat{u}(\omega, y) = C(\omega)e^{-y|\omega|}$ for some function $C(\omega)$. It is simply seen that $C(\omega) = \hat{f}(\omega)$ and therefore

$$u(x,y) = \mathcal{F}^{-1}\{\hat{u}\} = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{f}(\omega) e^{-\omega|y|} e^{i\omega x} d\omega.$$
(9.11)

Problem 9.17. Show that the above solution can be written in the following form

$$u(x,y) = \frac{y}{\pi} \int_{\mathbb{R}} \frac{f(\xi)}{y^2 + (x-\xi)^2} d\xi.$$
(9.12)

LAPLACE equation in quadrant

Now let us solve the LAPLACE equation in quadrant $\Omega = \{(x, y); x > 0, y > 0\}$ with boundary condition u(0, y) = 0 and u(x, 0) = f(x) for x > 0. To solve the problem, we extend the problem on the half-plane $\{(x, y), y > 0\}$ by extending f(x) as an odd function $f_{\text{odd}}(x)$ for $-\infty < x < \infty$. Now, formula (9.11) implies

$$u(x,y) = \frac{2}{\pi} \int_0^\infty \hat{f}_s(\omega) e^{-\omega|y|} \sin(\omega x) d\omega,$$

where $\hat{f}_s(\omega)$ is the sine FOURIER transform of f(x).

LAPLACE equation in a strip

Consider the following problem on strip $\Omega = \{(x, y); a < y < b\}$

$$\begin{cases} \Delta u = 0\\ u(x, a) = f(x), u(x, b) = g(x) \end{cases},$$

Since the domain is infinite in x-direction, we take the FOURIER transform with respect to x and obtain the following problem

$$\left\{ \begin{array}{l} \partial_{yy} \hat{u} - \omega^2 \hat{u} = 0 \\ \hat{u}(\omega, a) = \hat{f}(\omega) \\ \hat{u}(\omega, b) = \hat{g}(\omega) \end{array} \right.$$

The solution of the above equation is

$$\hat{u}(\omega, y) = A(\omega) e^{\omega y} + B(\omega) e^{-\omega y},$$

for some undetermined functions $A(\omega), B(\omega)$ which are determined by the aid of the given boundary conditions y = a and y = b as follows

$$\begin{cases} \hat{f}(\omega) = A(\omega) e^{\omega a} + B(\omega) e^{-\omega a} \\ \hat{g}(\omega) = A(\omega) e^{\omega b} + B(\omega) e^{-\omega b} \end{cases}.$$

Thus,

$$A(\omega) = \frac{\hat{f}(\omega) e^{-\omega b} - \hat{g}(\omega) e^{-\omega a}}{2\sinh(\omega(a-b))}, \quad B(\omega) = -\frac{\hat{f}(\omega) e^{\omega b} - \hat{g}(\omega) e^{\omega a}}{2\sinh(\omega(a-b))},$$

and finally

$$u(x,y) = \frac{1}{2\pi} \int_{\mathbb{R}} [A(\omega) e^{\omega y} + B(\omega) e^{-\omega y}] e^{i\omega x} d\omega.$$

9.2.2 Heat and wave problems

We solve simple heat and wave problem in 2D. In particular, we solve problems $\partial_t u = k \Delta u$, and $\partial_{tt} u = c^2 \Delta u$ on semi-bounded domains.

Solution to heat equation

We first find the form of heat kernel in \mathbb{R}^2 . For higher dimension, the form of the solution is completely similar. Consider the following problem

$$\begin{cases} \partial_t u = \Delta u, (x, y) \in \mathbb{R}^2\\ u(0, x, y) = u_0(x, y) \end{cases}.$$
(9.13)

If the solution u(t, x, y) has a transform \hat{u} , then it satisfies the following equation

$$\begin{cases} \partial_t \hat{u}(t, \omega_x, \omega_y) = -\omega^2 \, \hat{u}(t, \omega_x, \omega_y) \\ \hat{u}(0, \omega_x, \omega_y) = \hat{u}_0(\omega_x, \omega_y) \end{cases}$$

where $\omega = \sqrt{\omega_x^2 + \omega_y^2}$. The above equation is a linear ordinary equation with respect to t and thus

$$\hat{u}(t,\omega_x,\omega_y) = \hat{u}_0(\omega_x,\omega_y) e^{-\omega^2 t}.$$
(9.14)

This gives the solution u as follows

$$u(t,x,y) = \frac{1}{4\pi^2} \int_{\mathbb{R}^2} \hat{u}_0(\omega_x,\omega_y) \, e^{-\omega^2 t} \, e^{i\omega_x x} \, e^{i\omega_y y} \, d\omega_x \, d\omega_y. \tag{9.15}$$

By the convolution, we can write

$$u(t, x, y) = \mathcal{F}^{-1}\{\hat{u}_0(\omega_x, \omega_y) e^{-\omega^2 t}\} = u_0(x, y) * \mathcal{F}^{-1}\{e^{-(\omega_x^2 + \omega_y^2)t}\}$$

On the other hand, we have

$$\mathcal{F}^{-1}\left\{e^{-(\omega_x^2+\omega_y^2)t}\right\} = \frac{1}{4\pi t} e^{-\frac{(x^2+y^2)}{4t}}.$$
(9.16)

The functions

$$\Phi(t,x,y) = \frac{1}{4\pi t} e^{-\frac{(x^2+y^2)}{4t}}$$

is called the *fundamental solution* or the *heat kernel* of 2D heat problem. Therefore, the solution can be put in the following convolution form

$$u(t,x,y) = \frac{1}{4\pi t} \int_{\mathbb{R}^2} u_0(z_1,z_2) \, e^{-\frac{(x-z_1)^2 + (y-z_2)^2}{4t}} dz_1 \, dz_2.$$
(9.17)

Heat problems on semi-infinite domains

Consider the following heat problem on the half-plane y > 0:

$$\begin{cases} \partial_t u = \Delta u \\ u(t, x, 0) = 0 \\ u(0, x, y) = u_0(x, y) \end{cases}$$
(9.18)

If we extend $u_0(x, y)$ to \mathbb{R}^2 as an odd function with respect to y, then we reach a problem on \mathbb{R}^2 . Let $u_{\text{odd}}(x, y)$ be the odd extension of u_0 with respect to y in \mathbb{R}^2 . We have

$$u_{\rm odd}(t,x,y) = \frac{1}{4\pi^2} \int_{\mathbb{R}^2} \hat{u}_{\rm odd}(\omega_x,\omega_y) \, e^{-\omega^2 t} \, e^{i\omega_x x} \, e^{i\omega_y y} \, d\omega_x \, d\omega_y.$$

We claim $u_{\text{odd}}(t, x, 0) = 0$. In fact, $\hat{u}_{\text{odd}}(\omega_x, -\omega_y) = -\hat{u}_{\text{odd}}(\omega_x, \omega_y)$ and thus

$$\int_{\mathbb{R}^2} \hat{u}_{\text{odd}}(\omega_x, \omega_y) \, e^{-\omega^2 t} \, e^{i\omega_x x} \, e^{i\omega_y y} = i \int_{\mathbb{R}^2} \hat{u}_{\text{odd}}(\omega_x, \omega_y) \, e^{-\omega^2 t} \, e^{i\omega_x x} \sin(\omega_y y) \, dx$$

that verifies the claim. Therefore, we can write

$$u_{\rm odd}(t,x,y) = \frac{i}{4\pi^2} \int_{\mathbb{R}^2} \hat{u}_{\rm odd}(\omega_x,\omega_y) \, e^{-\omega^2 t} \, e^{i\omega_x x} \sin(\omega_y y) \, d\omega_x \, d\omega_y.$$

The solution u(t, x, y) then can be written as follows in the convolution form

$$u(t, x, y) = u_{\text{odd}}(x, y) * \Phi(t, x, y).$$

Non-homogeneous heat equations

Consider the following non-homogeneous equation

$$\begin{cases} \partial_t u = \Delta u \\ u(t, x, 0) = f(x) \\ u(0, x, y) = u_0(x, y) \end{cases}.$$

In order to solve the problem, we use the *superposition principle* and split up the problem into two sub-problems

$$\begin{cases} \Delta v = 0\\ v(x,0) = f(x) \end{cases} + \begin{cases} \partial_t w = \Delta w\\ w(t,x,0) = 0\\ w(0,x,y) = u_0(x,y) - v(x,y) \end{cases}$$

It is simply seen that the solution of the original problem is as follows

$$u(t, x, y) = v(x, y) + w(t, x, y).$$

The function $v_e(x, y)$ is called the *steady state* solution contributed by the boundary term. We have the following property

$$\lim_{t\to\infty} u(t,x,y) = v(x,y) + \lim_{t\to\infty} w(t,x,y) = v(x,y).$$

Solution to wave equations

Now, we consider the wave equation $\partial_{tt}u = c^2 \Delta u$ in \mathbb{R}^2 . For the sake of simplicity, we solve the following problem

$$\begin{cases} \partial_{tt} u = c^2 \Delta u \\ u(0, x, y) = f(x, y) \\ \partial_t u(0, x, y) = 0 \end{cases}.$$

The ordinary differential equation for $\hat{u}(t, \omega_x, \omega_y)$ is

$$\left\{ \begin{array}{l} \partial_{tt} \hat{u} + c^2 \omega^2 \hat{u} = 0 \\ \hat{u}(0, \omega_x, \omega_y) = \hat{f}(\omega_x, \omega_y) \\ \partial_t \hat{u}(0, \omega_x, \omega_y) = 0 \end{array} \right. ,$$

where $\omega = \sqrt{\omega_x^2 + \omega_y^2}$ as before. The solution of the above ordinary initial value problem is

$$\hat{u}(t,\omega_x,\omega_y) = \hat{f}(\omega_x,\omega_y)\cos(ct\omega).$$
(9.19)

Therefore, the solution u(t, x, y) can be written in the following convolution form

$$u(t, x, y) = f(x, y) * \mathcal{F}^{-1} \{ \cos(ct\omega) \}.$$
(9.20)

Let us try to find the inverse FOURIER transform in the above formula. To do that, we write ω_x, ω_y as $\omega_x = \omega \cos\gamma$, $\omega_y = \omega \sin\gamma$ for $\gamma \in [-\pi, \pi]$. Therefore, we can write

$$\mathcal{F}^{-1}\{\cos(ct\omega)\} = \frac{1}{4\pi^2} \int_{-\pi}^{\pi} \int_{0}^{\infty} \cos(ct\omega) e^{-i\omega(x\cos\gamma + y\sin\gamma)} \,\omega \,d\omega \,d\gamma.$$

If we write $x = \rho \cos\theta$, $y = \rho \sin\theta$, we reach

$$\mathcal{F}^{-1}\{\cos(ct\omega)\} = \frac{1}{4\pi^2} \int_{-\pi}^{\pi} \int_{0}^{\infty} \cos(ct\omega) \cos(\rho\omega\cos(\gamma-\theta))\omega d\omega d\gamma.$$

It turns out that

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(s\cos\gamma) \, d\gamma = J_0(s),$$

where J_0 is the BESSEL function of the first kind. Therefore, we have

$$\mathcal{F}^{-1}\{\cos(ct\omega)\} = \frac{1}{2\pi} \int_0^\infty J_0(\rho\omega) \cos(ct\omega)\omega d\omega.$$

We can write the right hand side of the above formula as follows

$$\frac{1}{2\pi} \int_0^\infty J_0(\rho\omega) \cos(ct\omega)\omega d\omega = \frac{1}{2\pi c} \frac{d}{dt} \frac{1}{\rho} \int_0^\infty J_0(\omega) \sin\left(\frac{ct}{\rho}\omega\right) d\omega.$$

We use the following formula

$$\int_0^\infty J_0(\omega) \sin\!\left(\frac{ct}{\rho}\omega\right) d\omega = \frac{1}{\sqrt{\frac{c^2t^2}{\rho^2} - 1}}, \rho < ct$$

and obtain

$$\mathcal{F}^{-1}\{\cos(ct\,\omega)\} = \frac{1}{2\pi c} \frac{d}{dt} \frac{1}{\sqrt{c^2 t^2 - \rho^2}}, \, \rho < ct.$$

Finally, the solution u(t, x, y) in formula (9.20) can be written as follows

$$u(t, x, y) = \frac{1}{2\pi c} \frac{d}{dt} \int_{B_{ct}(x, y)} \frac{f(z_1, z_2)}{\sqrt{c^2 t^2 - (x - z_1)^2 - (y - z_2)^2}} \, dz_1 dz_2,$$

where $B_{ct}(x, y)$ is the disk centered at (x, y) with radius ct. By a similar calculation, it is shown that if $\partial_t u(0, x, y) = g(x)$ then the solution is

$$\begin{split} u(t,x,y) = &\frac{1}{2\pi c} \frac{d}{dt} \int_{B_{ct}(x,y)} \frac{f(z_1,z_2)}{\sqrt{c^2 t^2 - (x-z_1)^2 - (y-z_2)^2}} \, dz_1 dz_2 + \\ &\frac{1}{2\pi c} \int_{B_{ct}(x,y)} \frac{g(z_1,z_2)}{\sqrt{c^2 t^2 - (x-z_1)^2 - (y-z_2)^2}} \, dz_1 dz_2. \end{split}$$

Problems

Problem 9.18. Solve the following heat equation on \mathbb{R}^2

$$\begin{cases} \partial_t u = 4\Delta u \\ u(0, x, y) = e^{-x^2 - y^2} \end{cases}$$

Problem 9.19. Consider the following heat problem in the upper half plane y > 0

$$\begin{cases} \partial_t u = \Delta u \\ u(t, x, 0) = e^{-|x|} \\ u(0, x, y) = e^{-x^2 - y^2} \end{cases}.$$

What method you suggest to solve this problem? Try it and write the solution in the integral form.

Problem 9.20. Solve the following heat equation on the upper half plane y > 0

$$\begin{cases} \partial_t u = \Delta u \\ \partial_y u(t, x, 0) = 0 \\ u(0, x, y) = e^{-|x|} e^{-y} \end{cases}.$$

Problem 9.21. Consider the LAPLACE equation

$$\begin{cases} \Delta u = 0\\ u(x,0) = f(x) \end{cases}$$

Show the the solution can be written as

$$u(x,y) = \frac{y}{\pi} \int_{\mathbb{R}} \frac{f(\xi)}{y^2 + (x-\xi)^2} d\xi.$$

At first glance, you may think $\lim_{y\to 0} u(x, y) = 0$. Plot the solution u(x, y) for y = 0.1, 0.05, 0.01 if $f(x) = e^{-|x|}$ and observe it converges to f(x).

Problem 9.22. Solve the LAPLACE equation on the domain $\Omega = \{(x, y), x > 0, y > 0\}$ with the boundary conditions u(0, y) = u(x, 1) = 0 and $u(x, 0) = e^{-x}$.

Problem 9.23. Write the solution of the following heat problem defined in the quadrant x > 0, y > 0 in the integral form

$$\begin{cases} \partial_t u = \Delta u \\ u(t, 0, y) = f(x) \\ u(t, x, 0) = 0 \\ u(0, x, y) = u_0(x, y) \end{cases}$$

Problem 9.24. Solve the LAPLACE equation $\Delta u = 0$ on the domain $\Omega = \{(x, y), 0 < x < 1\}$ with the boundary conditions u(0, y) = 0, $u(1, y) = e^{-y^2}$

Problem 9.25. Solve the LAPLACE equation on the domain $\Omega = \{(x, y), 0 < y < 1, x > 0\}$ with the boundary conditions u(0, y) = 0, u(x, 1) = 0 and $u(x, 0) = e^{-x^2}$

Problem 9.26. Let Ω denote the strip $\{(x, y); 0 < y < 1\}$

a) Show that the solution to the LAPLACE equation

s
$$\begin{cases} \Delta u = 0\\ u(x,0) = 0, u(x,1) = \delta(x+1) + \delta(x-1) \\ u(x,y) = \frac{2}{\pi} \int_0^\infty \frac{\sinh(\omega y)}{\sinh(\omega)} \cos(\omega) \cos(\omega x) \, d\omega. \end{cases}$$

is

b) Find a solution if the boundary data changes to $u(x,1) = \delta(x+1) - \delta(x-1).$

Problem 9.27. Solve the following heat problem in the strip $\Omega = \{(x, y); 0 < y < 1\}$

$$\left\{ \begin{array}{l} \partial_t u = \Delta u \\ u(t,x,0) = u(t,x,1) = 1 \\ u(0,x,y) = \left\{ \begin{array}{l} 1 & -1 < x < 1 \\ 0 & \text{otherwise} \end{array} \right. \end{array} \right. .$$