

Statistical Machine Learning II

International Undergraduate Summer Enrichment Program (IUSEP)

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Outline



Penalized Methods

Support Vector Machine

Software and Remark

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Ridge Regression

• The ridge regression coefficient estimates $\hat{\beta}^R$ are the values that minimize

$$\sum_{i} \left(y_i - \beta_0 - \sum_{j} \beta_j x_{ij} \right)^2 + \lambda \sum_{j} \beta_j^2,$$

where λ is a tuning parameter, to be determined separately.

- The second term $\lambda \sum_{j} \beta_{j}^{2}$ called a shrinkage penalty, is small when $\beta_{j}, j \ge 1$ are close to zero, and so it has the effect t of shrinking the estimates of β_{j} towards zero.
- The tuning parameter λ serves to control the relative impact of these two terms on the regression coefficient estimates.
- Selecting a good value for λ is critical; cross-validation is used for this.

Credit data example





As λ increases, the coefficients are shrunken to zeros.

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Penalized Methods

Scaling of predictors



- The standard least squares coefficient estimates are scale equivariant: multiplying X_j by a constant c simply leads to a scaling of the least squares coefficient estimates by a factor of 1/c. In other words, regardless of how the *j*-th predictor is scaled X_jβ̂_j will remain the same.
- In contrast, the ridge regression coefficient estimates can change substantially when multiplying a given predictor by a constant, due to the sum of squared coefficient term in the penalty part of the ridge regression objective function.
- Therefore, it is best to apply ridge regression after standardizing the predictors, using the formula

$$\tilde{x}_{ij} = x_{ij} / \sqrt{\sum_i (x_{ij} - \bar{x}_j)^2 / n}.$$

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Credit data example



Simulated data with n = 50 observations, p = 45 predictors, all having nonzero coefficient. Squared bias (black), variance (green), and test mean squared error (purple) for the ridge regression predictions on a simulated data set. The horizontal dashed lines indicate the minimum possible MSE. The purple crosses indicate the ridge regression models for which the MSE is smallest.

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- Ridge regression, unlike subset selection, will generally select models that involve just a subset of the variables, ridge regression will include all p predictors in the final model.
- The LASSO is a relatively recent alternative to ridge regression that overcomes this disadvantage. The lasso coefficient $\hat{\beta}^L$ minimize the quantity

$$\sum_{i} \left(y_i - \beta_0 - \sum_{j} \beta_i x_{ij} \right)^2 + \lambda \sum_{j} |\beta_j|,$$

where λ is a tuning parameter.

• The LASSO uses l_1 penalty instead of l_2 (ridge regression).

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- As with ridge regression, the lasso shrinks the coefficient estimates towards zero as λ increases.
- However, in the case of the lasso, the l₁ penalty has the effect of forcing some of the coefficient estimates to be exactly equal to zero when the tuning parameter λ is sufficientl large. Thus performs variable selection.
- We say that the lasso yields sparse models that is, models that involve only a subset of the variables.
- Selecting a good value for λ is critical; cross-validation is again used for this.

Credit data example





As λ increases, the coefficients are shrunken to exact zeros.

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Penalized Methods

Ridge regression and the LASSO



- Why is it that the lasso, unlike ridge regression, results in coefficient estimates that are exactly equal to zero?
- One can show that the lasso and ridge regression coefficient estimates solve the problems

$$\begin{split} \min_{\beta} \sum_{i} \left(y_{i} - \beta_{0} - \sum_{j} \beta_{i} x_{ij} \right)^{2}, \text{ subject to } \sum_{j} |\beta_{j}| \leq c; \\ \min_{\beta} \sum_{i} \left(y_{i} - \beta_{0} - \sum_{j} \beta_{i} x_{ij} \right)^{2}, \text{ subject to } \sum_{j} \beta_{j}^{2} \leq c; \end{split}$$

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Penalized Methods

Ridge regression and the LASSO





Credit data example





Left: Plots of squared bias (black), variance (green), and test mean squared error (purple) for the LASSO on a simulated data set. Right: Comparison of squared bias, variance and test MSE between lasso (solid) and ridge (dashed). The purple crosses indicate the LASSO models for which the MSE is smallest.

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Credit data example



Left: Plots of squared bias (black), variance (green), and test mean squared error (purple) for the LASSO on another simulated data set. Right: Comparison of squared bias, variance and test MSE between lasso (solid) and ridge (dashed). The purple crosses indicate the LASSO models for which the MSE is smallest.

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- These two examples illustrate that neither ridge regression nor the lasso will universally dominate the other.
- In general, one might expect the lasso to perform better when the response is a function of only a relatively small number of predictors.
- However, the number of predictors that is related to the response is never known a priori for real data sets.
- ► A technique such as cross-validation can be used in order to determine which approach is better on a particular data set.

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Separable Hyperplanes



- ► Imagine a situation where you have a two class classification problem with two predictors *X*₁ and *X*₂.
- Suppose that the two classes are linearly separable i.e. one can draw a straight line in which all points on one side belong to the first class and points on the other side to the second class.
- ► Then a natural approach is to find the straight line that gives the biggest separation between the classes i.e. the points are as far from the line as possible
- This is the basic idea of a support vector classifier.

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Hyperplane



- A hyperplane in p dimensions is a flat affine subspace of dimension p-1.
- ► In general the equation for a hyperplane has the form

$$\beta_0 + \beta_1 X_1 + \dots + \beta_p X_p = 0.$$

- In p = 2 dimensions a hyperplane is a line.
- If $\beta_0 = 0$, the hyperplane goes through the origin, otherwise not.
- ► The vector β = (β₁, · · · , β_p) is called the normal vector it points in a direction orthogonal to the surface of a hyperplane.

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Hyperplane in 2 Dimensions





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Separating Hyperplane



- If f(X) = β₀ + β₁X₁ + · · · + β_pX_p, then f(X) > 0 for points on one side of the hyperplane, and f(X) < 0 for points on the other.</p>
- ► If we code the colored points as $Y_i = +1$ as blue and $Y_i = -1$ as purple, then if $Y_i \cdot f(X_i) > 0$ for all i, f(X) = 0 defines a Separating Hyperplane.

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Hard Margin

- Among all separating hyperplanes, find the one that makes the biggest gap or margin between the two classes.
- Constrained optimization problem

maximize
$$\beta_{0,\beta_{1},\cdots,\beta_{p}}M$$

subject to $\sum_{j=1}^{p} \beta_{j}^{2} = 1$
 $y_{i}(\beta_{0} + \beta_{1}X_{1} + \cdots + \beta_{p}X_{p}) \ge M$
for $i = 1, \cdots, n$.



► This can be rephrased as a convex quadratic program, and solved efficiently. The function svm() in package e1071 solves this problem efficiently.

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Hard Margin



- The data on the left are not separable by a linear boundary.
- In general it is true for n < p.



Hard Margin





Sometimes the data are separable, but noisy. This can lead to a poor solution for the maximal-margin (hard margin) classifier. boundary.

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Soft Margin





• The support vector classifier maximizes a soft margin.

maximize_{\beta_0,\beta_1,\cdots,\beta_p;\epsilon_1,\cdots,\epsilon_n}M; subject to
$$\sum_{j=1}^p \beta_j^2 = 1$$

 $y_i(\beta_0 + \beta_1 X_1 + \cdots + \beta_p X_p) \ge M(1 - \epsilon_i)$
 $\epsilon_i \ge 0, \sum_{i=1}^n \epsilon_i \le C.$

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C is a regularization parameter and represent the price we need to pay to separate the two classes.

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Support Vectors





Only those support vectors determine the optimization solution for both hard margin and soft margin.

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Linear boundary can fail



- Sometime a linear boundary simply won't work, no matter what value of *C*.
- ► For example, in the situation shown above.
- What do we do? the kernel trick!!!

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Feature Expansion





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Feature Expansion



- Enlarge the space of features by including transformations; for example $X_1^2, X_2^3, X_1X_2, X_1X_2^2, \cdots$, Hence go from a *p*-dimensional space to a M > p dimensional space.
- ► Fit a support-vector classifier in the enlarged space.
- ► This results in non-linear decision boundaries in the original space.
- Example: Suppose we use $(X_1, X_2, X_1^2, X_2^2, X_1X_2)$ instead of just (X_1, X_2) . Then the decision boundary would be of the form

$$\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_1^2 + \beta_4 X_2^2 + \beta_5 X_1 X_2 = 0.$$

This leads to nonlinear decision boundaries in the original space (quadratic conic sections).

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Cubic Polynomials



- Here we use a basis expansion of cubic polynomials — from 2 variables to 9.
- The support-vectorclassifier in the enlarged space solves the problem in the lower-dimensional space



The decision boundary is

 $\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_1^2 + \beta_4 X_2^2 + \beta_5 X_1 X_2 + \beta_6 X_1^3 + \beta_7 X_2^3 + \beta_8 X_1 X_2^2 + \beta_9 X_1^2 X_2 = 0.$

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Nonlinearities and Kernels



- Polynomials (especially high-dimensional ones) get wild rather fast.
- There is a more elegant and controlled way to introduce nonlinearities in support vector classifier — through the use of kernels.
- Before we discuss these, we must understand the role of inner products in support vector classifier.

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Inner products and kernels



$$\langle x_i, x_{i'} \rangle = \sum_j x_{ij} x_{i"j}.$$

► The linear support vector classifier can be represented as

$$f(x) = \beta_0 + \sum_i \alpha_i \langle x, x_i \rangle$$

- ► To estimate parameters $\alpha_1, \dots, \alpha_n$ and β_0 , all we need are $\binom{n}{2}$ inner products $\langle x, x_i \rangle$ between all pairs of training observations.
- It turns out that most of the $\hat{\alpha}_i$ can be zero

$$f(x) = \beta_0 + \sum_{i \in S} \hat{\alpha}_i \langle x, x_i \rangle,$$

where S is the support set of indices *i* such that $\hat{\alpha}_i > 0$.

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Kernels and Support Vector Machine



- If we can compute inner products between observations, we can fit a support vector classifier — can be very abstract!
- Some special kernel function can do this for us. E.g.

$$K(x_i, x_{i'}) = (1 + \sum_j x_{ij} x_{i'j})^2$$

computes the inner products needed for d dimensional polynomials — $\binom{p+d}{d}$ basis functions!

• The solotion has the form

$$f(x) = \beta_0 + \sum_{i \in S} \hat{\alpha}_i K(x, x_i).$$

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Radial Kernel



The radial Kernel has the format

$$K(x_i, x_{i'}) = \exp\left(-\gamma \sum_j (x_{ij} - x_{i'j})^2\right),$$

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where γ is tuning parameter.

The decision bounady is,

$$f(x) = \beta_0 + \sum_{i \in S} \hat{\alpha}_i K(x, x_i),$$

implicit feature space; very high dimensional.

 Controls variance by squaring down most dimenions severely.



Example - Heart Data



ROC curves on Training data

▶ ROC curve is obtained by changing the threshold 0 to threshold *t* in $\hat{f}(X) > t$, and recording false positive and true positive rates as *t* varies.

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Example - Heart Data



ROC curves on Testing data

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SVMs: More than 2 classes



- ► The SVM as defined works for K = 2 classes. What do we do if we have K > 2 classes?
- ▶ OVA One versus All. Fit *K* different 2-class SVM classifiers $\hat{f}_k(x)$, $k = 1, \dots, K$; each class versus the rest. Classify x^* to the class for which $\hat{f}_k(x^*)$ is largest.
- ▶ OVO One versus One. Fit all $\binom{K}{2}$ pairwise classifiers $\hat{f}_{kl}(x)$. Classify x^* to the class that wins the most pairwise competitions.
- ▶ Which one to choose? If *K* is not too large, use OVO.

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Software and Remark

Summary and Remark



- ► Install software **R**, if necessary, play demos, browse documentation.
- In my opinion, the best way to learn in this course is to try everything in R.
- Once it works, then think why, and how to write it in your own way.

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