



## SOME MORE (NEW) DEFINITIONS

Let  $\mathcal{C}$  be a rigid monoidal category

→ A **PIVOTAL STRUCTURE** on  $\mathcal{C}$  is a monoidal natural isomorphism  $a : \text{Id}_{\mathcal{C}} \rightarrow (-)^{**}$

→ Using the pivotal structure, we can define the trace of any  $f \in \text{End}_{\mathcal{C}}(X)$  as

$$\text{Tr}(f) = \begin{array}{c} \text{---} X \text{---} \\ \boxed{f} \\ \text{---} X \text{---} \\ \boxed{a_X} \\ \text{---} X^{**} \text{---} \end{array} \in \text{End}(\mathbb{1}) = \mathbb{k}$$

→ Define  $\dim(X) = \text{Tr}(\text{Id}_X)$

→ A pivotal structure is called **SPHERICAL** if  $\dim(X) = \dim(X^*) \quad \forall X \in \mathcal{C}$

→  $\mathcal{C}$  is called **PIVOTAL (SPHERICAL)** if it is equipped with a pivotal (spherical) structure  $a$ .

→ The following properties of trace are easy to check on a spherical category.

- $\text{Tr}(f \otimes g) = \text{Tr}(f) \text{Tr}(g)$

- $\text{Tr}(f \oplus g) = \text{Tr}(f) + \text{Tr}(g)$

- $\text{Tr}(f \circ g) = \text{Tr}(g \circ f)$  for  $f: X \rightarrow Y$   
 $g: Y \rightarrow X$

- $\text{Tr}(\alpha f) = \alpha \text{Tr}(f)$  for  $\alpha \in \mathbb{K}$

- $\text{Tr}(f) = \text{Tr}(f^*)$

# CONNECTION BETWEEN RIBBON TWISTS and PIVOTAL / SPHERICAL STRUCTURE

Now,  $\mathcal{C}$  is a braided tensor category.

→ Let  $\psi = \{ \psi_x = u_x \theta_x : x \rightarrow x^{**} \}_{x \in \mathcal{C}}$  Then,

$$\left\{ \begin{array}{l} \psi \text{ is a pivotal} \\ \text{structure on } \mathcal{C} \end{array} \right\} \iff \left\{ \theta \text{ is a twist} \right\}$$

→ Suppose  $\mathcal{C}$  is further a fusion category. Then,

[Prop 8.10.12] 
$$\left\{ \begin{array}{l} \psi \text{ is a spherical} \\ \text{structure on } \mathcal{C} \end{array} \right\} \iff \left\{ \theta \text{ is a ribbon} \right\}$$

## § 8.3 The S-matrix of a Premodular Category

For this talk,  $\mathbb{k} =$  alg. closed field of char. 0

Defn (PRE-MODULAR CATEGORY)

A monoidal category  $\mathcal{C}$  is called **PRE-MODULAR** if

(i)  $\mathcal{C}$  is fusion,

(ii)  $\mathcal{C}$  is braided, and

(iii)  $\mathcal{C}$  has a ribbon structure  $\theta$ .

By Prop 8.10.12, (iii) is equivalent to

(iii)'  $\mathcal{C}$  has a spherical structure  $\gamma$ .

## NOTATION:

- $\mathcal{O}(\mathcal{C}) =$  isomorphism classes of simple objects in  $\mathcal{C}$
- For  $x, y, z \in \mathcal{O}(\mathcal{C})$   
 $N_{x,y}^z =$  multiplicity of  $z$  in  $x \otimes y$

## Defn:

→ Let  $\mathcal{C}$  be a pre-modular category. The **S-MATRIX** of  $\mathcal{C}$  is defined by

$$S := (s_{x,y})_{x,y \in \mathcal{O}(\mathcal{C})} \quad \text{where} \quad s_{x,y} = \text{Tr}(c_{y,x} c_{x,y})$$

→ A pre-modular category is said to be **MODULAR** if the S-matrix is non-degenerate.

## SOME OBSERVATIONS :

→ S-matrix is symmetric

$$\delta_{x,y} = \text{Tr}(C_{y,x} C_{x,y}) = \text{Tr}(C_{x,y} C_{y,x}) = \delta_{y,x}$$

$$\rightarrow \delta_{x,\mathbb{1}} = \text{Tr}(C_{\mathbb{1},x} \circ C_{x,\mathbb{1}})$$

but  $C_{x,\mathbb{1}} = C_{\mathbb{1},x} = \text{id}_x$

$$= \text{Tr}(\text{id}_x)$$

$$= \dim(X)$$

$$\begin{aligned} \rightarrow \delta_{x^*,y^*} &= \text{Tr}(C_{y^*,x^*} \circ C_{x^*,y^*}) = \text{Tr}(C_{y,x}^* \circ C_{x,y}^*) \\ &= \text{Tr}((C_{x,y} \circ C_{y,x})^*) \\ &= \text{Tr}(C_{x,y} \circ C_{y,x}) \\ &= \delta_{x,y} \end{aligned}$$

# EXAMPLE 1

$G$  finite abelian group

$q: G \rightarrow \mathbb{R}^\times$  quadratic form on  $G$

$b: G \times G \rightarrow \mathbb{R}^\times$  associated symm. bilinear form

→ Consider the pointed braided fusion category  $\mathcal{C}(G, q)$  defined in Sean's talk.

[recall  $q \leftrightarrow (w, c)$  then  $\mathcal{C}(G, q) = (\text{Vec}_G^w, c)$   
and  $q = c \circ \Delta$ ]

→ These categories have a canonical ribbon structure

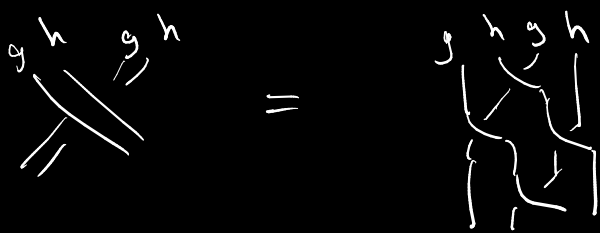
$$\theta_g = q(g) \text{Id}_{s_g}$$

w.r.t this ribbon structure,

$$\dim(s_g) = 1$$

(easy exercise)



Now, 

$$\Rightarrow c(gh, gh) = c(g, h) c(g, g) c(h, h) c(h, g)$$

$$\Rightarrow q(gh) = q(g)q(h) c(g, h) c(h, g)$$

$$\therefore c(g, h) c(h, g) = \frac{q(gh)}{q(g)q(h)} = b(g, h)$$

$$\begin{aligned} \therefore \mathcal{S}_{\mathfrak{g}_g, \mathfrak{g}_h} &= \text{Tr} (c_{\mathfrak{g}_h, \mathfrak{g}_g} \circ c_{\mathfrak{g}_g, \mathfrak{g}_h}) = \text{Tr} (b(g, h) \text{Id}_{\mathfrak{g}_{gh}}) \\ &= b(g, h) \text{Tr} (\text{Id}_{\mathfrak{g}_{gh}}) \\ &= b(g, h) \dim(\mathfrak{g}_{gh}) \\ &= b(g, h) \end{aligned}$$

The last example can be generalized.

PROP 8.13.8: We have

$$s_{xy} = \theta_x^{-1} \theta_y^{-1} \sum_{z \in \mathcal{O}(e)} N_{xy}^z \theta_z \dim(z) \quad \forall x, y \in \mathcal{O}(e)$$

PROOF: Recall the twist  $\theta$  satisfies

$$\theta_{x \otimes y} = (\theta_x \otimes \theta_y) \circ c_{y,x} \circ c_{x,y}$$

Apply  $\text{Tr}$  to both sides to get

$$\begin{aligned} \text{LHS} &= \text{Tr}(\theta_{x \otimes y}) \\ &= \sum_{z \in \mathcal{O}(e)} N_{xy}^z \text{Tr}(\theta_z) \end{aligned}$$

(But  $z$  is simple  $\Rightarrow \theta_z = \theta_z \text{Id}_z$   
where  $\theta_z \in k$ )

$$= \sum_{z \in \mathcal{O}(e)} N_{xy}^z \theta_z \text{Tr}(\text{Id}_z) = \sum_{z \in \mathcal{O}(e)} N_{xy}^z \theta_z \dim(z)$$

$$\left( \begin{aligned} X \otimes Y &= \bigoplus_{z \in \mathcal{O}(e)} z^{\oplus N_{xy}^z} \\ \text{and } \theta_{x \otimes y} &= \bigoplus_{z \in \mathcal{O}(e)} \theta_z^{\oplus N_{xy}^z} \\ \text{and } \text{Tr} &\text{ is additive} \end{aligned} \right)$$

$$\text{RHS} = \text{Tr}((\Theta_x \otimes \Theta_y) \circ C_{Y,X} \circ C_{X,Y})$$

Notice that since  $X$  is simple,  $\Theta_x = \Theta_x \text{id}_X$

$$\Theta_y = \Theta_y \text{id}_Y$$

$$\Theta_x, \Theta_y \in \mathbb{k}$$

$$\therefore \text{RHS} = \Theta_x \Theta_y \text{Tr}(C_{Y,X} \circ C_{X,Y})$$

$$= \Theta_x \Theta_y \delta_{X,Y}$$

Comparing with LHS, we get

$$\delta_{X,Y} = \frac{1}{\Theta_x \Theta_y} \sum_{Z \in \text{Obj}(\mathcal{C})} N_{X,Y}^Z \Theta_Z \dim(Z)$$

Remark: The above proof holds even if  $\mathcal{C}$  is not finite.

For  $\ell = \ell(G, q)$

$$\Theta_{\delta_g} = q(g) \quad ,$$

$$\dim(\delta_g) = 1 \quad \forall g \in G$$

$$N_{\delta_g, \delta_h}^{\delta_{gh}} = 1 \quad \text{and} \quad N_{a,b}^c = 0 \quad \text{else}$$

By Prop 8.13.8 ,

$$\Delta_{\delta_g, \delta_h} = \frac{1}{q(g)q(h)} N_{\delta_g, \delta_h}^{\delta_{gh}} q(gh)$$

$$= \frac{q(gh)}{q(g)q(h)}$$

$$= b(g, h)$$

# GROTHENDIECK RINGS

Let  $\mathcal{C}$  be an abelian category.

Defn: An object  $X \in \mathcal{C}$  is said to be of **finite length** if  $\exists$  a filtration, that is, a sequence of morphisms

$$0 = X_0 \xrightarrow{f_1} X_1 \xrightarrow{f_2} X_2 \cdots \hookrightarrow X_{n-1} \xrightarrow{f_n} X_n = X$$

such that each  $f_i$  is a monomorphism and  $X_i / X_{i-1} = \text{coker } f_i$  is simple in  $\mathcal{C}$ .

$\rightarrow$  Such a filtration is called a **Jordan-Hölder series** of  $X$ . A simple object  $Y$  has **multiplicity**  $m$  in  $X$  if we can find  $m$  different values of  $i$  such that  $X_i / X_{i-1} \cong Y$ .

## JORDAN-HÖLDER THEOREM :

Suppose that  $X \in \mathcal{C}$  has finite length. Then any filtration can be extended to a Jordan-Hölder series, and any two Jordan-Hölder series of  $X$  contain any simple object with the same multiplicity, so in particular have the same length.

→ As a consequence, for any  $X, Y \in \mathcal{C}$  with  $Y$  simple, we can define

$$[X:Y] = \text{multiplicity of } Y \text{ in the Jordan-Hölder series of } X$$

→ **length** of  $X$  is the length of its Jordan-Hölder series.

# GIROTHENDIECK GROUP:

Denoted  $\text{Gr}(\mathcal{C})$ , this is the free abelian group generated by isomorphism classes  $X_i, i \in I$  of simple objects in  $\mathcal{C}$ .

→ To every object  $X \in \mathcal{C}$ , we can canonically associate its class  $[X] \in \text{Gr}(\mathcal{C})$  given by the formula

$$[X] = \sum_i [X : X_i] X_i$$

→ For any exact sequence  $0 \rightarrow X \rightarrow Y \rightarrow Z \rightarrow 0$   
we have that  $[Y] = [X] + [Z]$  (How?)

Example: For the category  $\mathcal{C} = \text{Vec}_G$ ,  
 $\text{Gr}(\mathcal{C}) = \mathbb{Z}G$

• Let  $\mathcal{C}$  be a tensor category

(Note that rigidity and  $\text{End}_{\mathcal{C}}(\mathbb{1}) = \mathbb{k}$  are not required)

The tensor product on  $\mathcal{C}$  induces a natural multiplication on  $\text{Gr}(\mathcal{C})$  given by

$$(*) \quad X_i X_j = [X_i \otimes X_j] = \sum_{k \in I} [X_i \otimes X_j : X_k] X_k$$

$i, j \in I$

(\*) is called the **fusion rule** of  $\mathcal{C}$

Lemma 4.5.1: The above multiplication on  $\text{Gr}(\mathcal{C})$  is associative. The resulting ring is denoted  $K_0(\mathcal{C})$

Defn:  $K_0(\mathcal{C})$  is called the **Grothendieck ring** of  $\mathcal{C}$ .



## FROBENIUS-PERRON THEOREM (trimmed version of THM 3.2.1, EGNO)

Let  $B$  be a square matrix with non-negative real entries. Then:

→  $B$  has a largest non-negative eigenvalue  $\lambda(B)$ .

→  $\exists$  an eigenvector  $v$  of  $B$  with eigenvalue  $\lambda(B)$  with all entries non-negative.

## FROBENIUS-PERRON DIMENSION

Given a <sup>finite</sup> tensor category  $\mathcal{C}$  and a simple  $X_i \in \mathcal{C}$  consider the  $n \times n$  matrix  $N_i$  (where  $n = |\mathcal{I}|$ ) with

$$(N_i)_{j,k}^l = [X_i \otimes X_j : X_k] \in \mathbb{Z}_+ \quad j, k \in \mathcal{I}$$

Then  $\text{FPdim}(X_i) := \lambda(N_i)$

→ Extending additively, we get a ring homomorphism

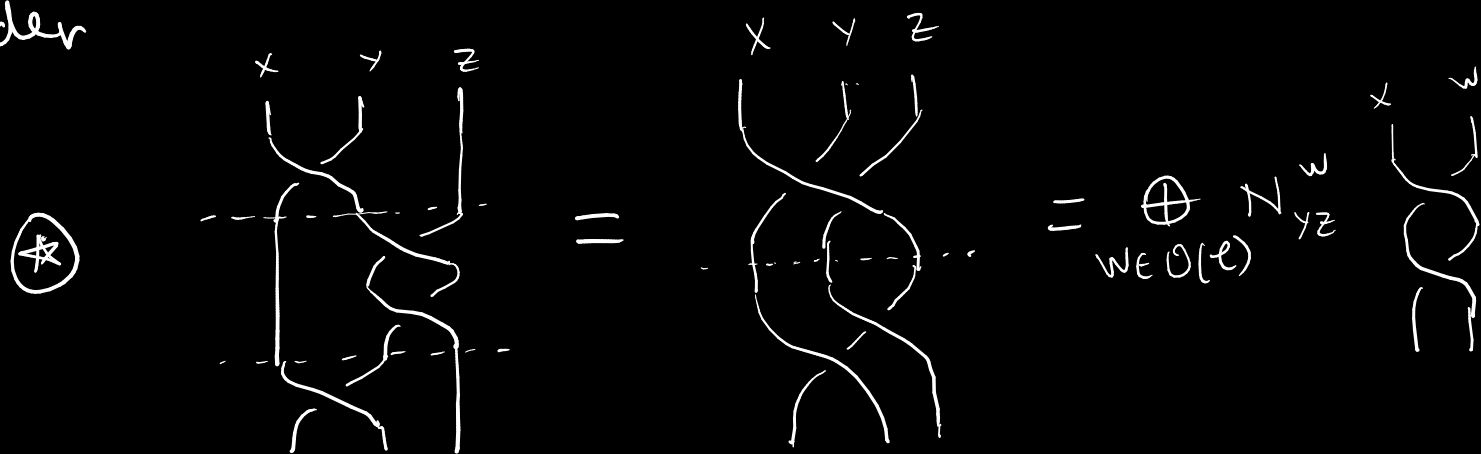
$$\text{FPdim} : \text{Gr}(\mathcal{C}) \longrightarrow \mathbb{C}$$

# Some more properties of $\delta_{x,y}$

Prop 8.13.10:  $\delta_{x,y}$  satisfy the relation

$$\delta_{x,y} \delta_{x,z} = \dim(X) \sum_{w \in \mathcal{O}(e)} N_{yz}^w \delta_{xw} \quad x, y, z \in \mathcal{O}(e)$$

PROOF: Consider



Notice that  $\in \text{End}(X) \cong \mathbb{k} \Rightarrow$   $= \alpha \int^x$

Taking trace  $\Rightarrow \delta_{x,z} = \alpha \dim(X) \Rightarrow \alpha = \frac{\delta_{x,z}}{\dim(X)}$

$$\text{Trace of LHS of } \textcircled{*} = \text{Tr} \left( \begin{array}{c} x \quad y \quad z \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \right) = \frac{\delta_{xz}}{\dim(X)} \text{Tr} \left( \begin{array}{c} x \quad y \\ \text{---} \\ \text{---} \end{array} \right) \\ = \frac{\delta_{xz} \delta_{xy}}{\dim(X)}$$

$$\text{Trace of RHS} = \sum_{w \in \theta(\mathfrak{e})} N_{yz}^w \delta_{x,w}$$

Comparing these we get the desired relation.

Remark: This proof remains valid when  $\mathfrak{e}$  is not finite.

• when  $\dim(X) = 0$ , then putting  $y = z$  yields

$$\delta_{xy}^2 = 0$$

$$\Rightarrow \delta_{x,y} = 0 \quad \forall y \in \theta(\mathfrak{e})$$

PROP 8.13.11:

(i) For any fixed  $x \in \mathcal{O}(\mathfrak{e})$  the map

$$h_x: \gamma \mapsto \frac{\delta_{x\gamma}}{\dim(X)}, \quad \gamma \in \mathcal{O}(\mathfrak{e})$$

defines a homomorphism  $K_0(\mathfrak{e}) \rightarrow \mathbb{k}$

(ii) The numbers  $\frac{\delta_{x\gamma}}{\dim(X)}$  are algebraic integers.

PROOF:

$$\begin{aligned} \text{(i) } h_x(\gamma z) &= h_x\left(\sum N_{\gamma z}^w w\right) = \sum N_{\gamma z}^w h_x(w) \\ &= \sum N_{\gamma z}^w \frac{\delta_{xw}}{\dim(X)} \end{aligned}$$

$$\begin{aligned} h_x(\gamma) h_x(z) &= \frac{\delta_{x\gamma}}{\dim(X)} \frac{\delta_{xz}}{\dim(X)} \\ &= \frac{\dim(X) \sum N_{\gamma z}^w \delta_{xw}}{\dim(X)^2} \quad (\text{by Prop 8.13.10}) \\ &= h_x(\gamma z) \end{aligned}$$

(ii) Let  $\vec{s}_x$  be the  $1 \times n$  matrix with  $(\vec{s}_x)_w = s_{x,w}$  for  $w \in \mathcal{O}(\mathfrak{e})$

Let  $(\vec{N}_y)$  be the  $n \times n$  matrix with  $(\vec{N}_y)_z^w = N_{y,z}^w$

then

$$\boxed{s_{xy} s_{xz} = \dim(x) \sum_{w \in \mathcal{O}(\mathfrak{e})} N_{yz}^w s_{xw}}$$

$$\Rightarrow \frac{s_{xy}}{\dim(x)} \vec{s}_x = \vec{N}_y \vec{s}_x$$

$\Rightarrow h_x(y)$  is an eigenvalue  
 $\therefore$  root of characteristic poly.  
 $\Rightarrow$  it's an algebraic integer

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### Remarks:

$\rightarrow$  If  $\dim(x) \neq 0$  then Prop 8.10.11 (i) holds for  $x$  with same proof even if  $\mathfrak{e}$  is not finite.

$\rightarrow$  When  $\dim(x) \neq 0$ , part (ii) holds when  $\mathfrak{e}$  is finite

# TRACE OF FACTORS OF MORPHISMS BETWEEN TENSOR PRODUCTS

Consider  $f: X \otimes Y \rightarrow X \otimes Y$



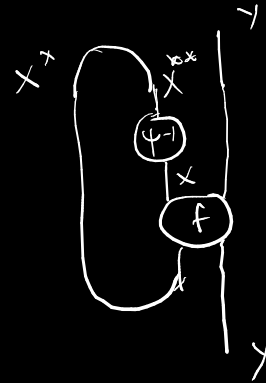
Define trace on X

$$\text{id}_X \otimes \text{Tr}(f) :=$$



Define trace on Y

$$\text{Tr} \otimes \text{id}_Y (f) :=$$



## T-Matrix :

It is an  $n \times n$  matrix ( $n = |O(e)|$ )  
where  $T = \text{diag}(\theta_i)$

→ The pair of matrices  $\{S, T\}$  for any modular category is called its **MODULAR DATA**.

→ A lot of information about the modular category can be obtained from the modular data.