

# CHE 572: ASSIGNMENT #1.

## SOLUTIONS.

$$\textcircled{1} \quad f(x) = \begin{bmatrix} f_1(x) \\ f_2(x) \end{bmatrix} = \begin{bmatrix} x_1^2 + 6x_1x_2 + x_2^2 + 4x_1 + 3x_2 + 12 \\ 2x_1^2 + 2x_2^2 - 2x_1x_2 \end{bmatrix} = 0$$

Jacobian of  $f(x)$ :

$$J[f(x)] = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} \begin{array}{l} \bullet \frac{\partial f_1}{\partial x_1} = 2x_1 + 6x_2 + 4. \\ \bullet \frac{\partial f_1}{\partial x_2} = 6x_1 + 2x_2 + 3. \\ \bullet \frac{\partial f_2}{\partial x_1} = 4x_1 - 2x_2. \end{array}$$

Substituting the differential terms into the expression

$$J[f(x)]: \bullet \frac{\partial f_2}{\partial x_2} = 4x_2 - 2x_1.$$

$$J[f(x)] = \begin{bmatrix} 2x_1 + 6x_2 + 4 & 6x_1 + 2x_2 + 3 \\ 4x_1 - 2x_2 & 4x_2 - 2x_1 \end{bmatrix}$$

$$\textcircled{2} \quad r(x) = \frac{\mu_{\max} x_1 x_2}{K_m + x_2}$$

Gradient of  $r(x)$  is given as:

$$\nabla r(x) = \frac{\partial r}{\partial x_1} \hat{i} + \frac{\partial r}{\partial x_2} \hat{j} \quad \text{--- (2a)}$$

$$\begin{aligned} \text{Now, } \frac{\partial r}{\partial x_1} &= \frac{\mu_{\max} x_2}{K_m + x_2} ; \frac{\partial r}{\partial x_2} = \frac{(K_m + x_2) \mu_{\max} x_1 - \mu_{\max} x_1 x_2}{[K_m + x_2]^2} \\ &= \frac{K_m \mu_{\max} x_1}{[K_m + x_2]^2} \end{aligned}$$

Substituting the differential terms into (2a):

$$\nabla r = \left[ \frac{\mu_{\max} x_2}{k_m + x_2} \hat{i} + \frac{k_m \mu_{\max} x_1}{[k_m + x_2]^2} \hat{j} \right]$$

(3) a)

Second-order Taylor series expansion of a single variable function  $f(x)$  about  $x=x_0$  is given as:

$$f(x) \approx f(x_0) + \left. \frac{df(x)}{dx} \right|_{x=x_0} (x-x_0) + \frac{1}{2!} \left. \frac{d^2f(x)}{dx^2} \right|_{x=x_0} (x-x_0)^2 \quad \text{---(3a)}$$

When  $f(x) = xe^{-x}$ , the differential terms in Eq. (3a) can be written as:

$$\frac{df(x)}{dx} = e^{-x} - xe^{-x} = (1-x)e^{-x};$$

$$\frac{d^2f(x)}{dx^2} = -e^{-x} - e^{-x} + xe^{-x} = (x-2)e^{-x}$$

Substituting the differential terms into (3a) yields:

$$xe^{-x} \approx x_0 e^{-x_0} + (1-x_0)e^{-x_0} (x-x_0) + \frac{1}{2!} (x_0-2)e^{-x_0} (x-x_0)^2$$

b) Second order Taylor series expansion of a multivariable function  $f(\underline{x})$  about  $\underline{x}_0$  is given as:

$$f(\underline{x}) \approx f(\underline{x}_0) + \left. \nabla f(\underline{x}) \right|_{\underline{x}=\underline{x}_0} (\underline{x}-\underline{x}_0) + \frac{1}{2!} (\underline{x}-\underline{x}_0)^T \left. \nabla^2 f(\underline{x}) \right|_{\underline{x}=\underline{x}_0} (\underline{x}-\underline{x}_0)$$

When  $f(\underline{x}) = \frac{\mu_{\max} x_1 x_2}{k_m + x_2}$  and  $\underline{x} = [x_1 \ x_2]$   
 $\underline{x}_0 = [x_1^0 \ x_2^0]$ , the differential terms in (3b) can be calculated as follows:

Jacobian matrix  $\rightarrow \nabla f(\underline{x}) = \begin{bmatrix} \frac{\partial f(\underline{x})}{\partial x_1} & \frac{\partial f(\underline{x})}{\partial x_2} \end{bmatrix}$

Hessian matrix  $\rightarrow \nabla^2 f(\underline{x}) = \begin{bmatrix} \frac{\partial^2 f(\underline{x})}{\partial x_1^2} & \frac{\partial^2 f(\underline{x})}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f(\underline{x})}{\partial x_2 \partial x_1} & \frac{\partial^2 f(\underline{x})}{\partial x_2^2} \end{bmatrix}$  Where:

$$\frac{\partial f(\underline{x})}{\partial x_1} = \frac{\mu_{\max} x_2}{k_m + x_2};$$

$$\frac{\partial f(\underline{x})}{\partial x_2} = \frac{k_m \mu_{\max} x_1}{[k_m + x_2]^2};$$

$$\frac{\partial^2 f(\underline{x})}{\partial x_1^2} = 0; \quad \frac{\partial^2 f(\underline{x})}{\partial x_1 \partial x_2} = \frac{\partial^2 f(\underline{x})}{\partial x_2 \partial x_1} = \frac{k_m \mu_{\max}}{[k_m + x_2]^2};$$

$$\frac{\partial^2 f(\underline{x})}{\partial x_2^2} = -\frac{2k_m \mu_{\max} x_1}{[k_m + x_2]^3}.$$

Substituting the differential terms into (3b) yields:

$$f(\underline{x}) \approx \frac{\mu_{\max} x_1^0 x_2^0}{k_m + x_2^0} + \begin{bmatrix} \frac{\mu_{\max} x_2^0}{k_m + x_2^0} & \frac{k_m \mu_{\max} x_1^0}{[k_m + x_2^0]^2} \end{bmatrix} [\underline{x} - \underline{x}_0]$$

$$+ \frac{1}{2!} [\underline{x} - \underline{x}_0]^T \begin{bmatrix} 0 & \frac{k_m \mu_{\max}}{[k_m + x_2^0]^2} \\ \frac{k_m \mu_{\max}}{[k_m + x_2^0]^2} & -\frac{2k_m \mu_{\max} x_1^0}{[k_m + x_2^0]^3} \end{bmatrix} [\underline{x} - \underline{x}_0].$$

④ a)

<u>Solver</u>	<u>Method</u>
ode45	Runge-kutta
ode23	Runge-kutta
ode113	Adams-Bashforth-Moulton
ode15s	Numerical differentiation formulas
ode23s	Rosenbrock formula
ode23t	Trapezoidal rule
ode23tb	Trapezoidal + backward differentiation formula

b)

$$\begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix} \frac{dx}{dt} = \begin{bmatrix} 10^6 & 0 \\ 0 & 1 \end{bmatrix} x + \begin{bmatrix} 473 \\ 5 \end{bmatrix} u$$

inverting the matrix premultiplying  $\frac{dx}{dt}$  term, we obtain

the state-space model in the standard form:

$$\frac{dx}{dt} = \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 10^6 & 0 \\ 0 & 1 \end{bmatrix} x + \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 473 \\ 5 \end{bmatrix} u$$

$$\frac{dx}{dt} = \begin{bmatrix} 0 & 0.5 \\ 10^6 & 0 \end{bmatrix} x + \begin{bmatrix} 2.5 \\ 473 \end{bmatrix} u$$

$$\hookrightarrow \underline{A}$$

The eigenvalues of  $\underline{A}$  are:  $707.1068$ ;  $-707.1068$ .

from the eigenvalues of  $\underline{A}$ , it is evident that the dynamics of both  $x_1$  and  $x_2$  change equally fast. The opposite signs just indicate the direction of that change.

Therefore, the given set of ODEs constitute a non-stiff problem for which, use of any Runge-kutta based solver would suffice.

c) ode45: (i) Non-stiff problem solver (ii) medium order of accuracy. (iii) Computationally fast.

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Notations.

$M_T$ : Total mass of the liquid inside the kettle (grams)

$V_T$ : Total volume of the liquid inside the kettle (litres).

$S$ : Mass fraction of substrate

$E$ : Mass fraction of ethanol.

$Y$ : Mass fraction of yeast.

$M_E$ : Mass of ethanol inside the kettle (grams)

$M_S$ : Mass of substrate " " " (grams)

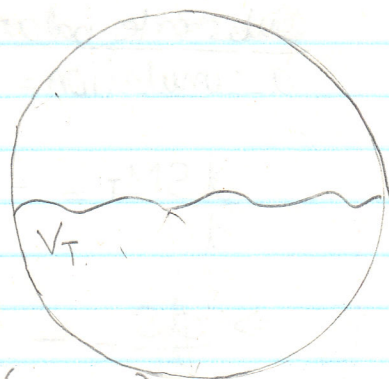
$M_Y$ : Mass of yeast " " " (grams)

$M_W$ : Mass of water " " " (grams)

$\rho$ : density of liquid at any given time 't' (grams/litre)

$S_0$ : initial mass fraction of substrate

$E_0$ : initial mass fraction of ethanol.



a)

Variables	INPUTS		OUTPUTS			States
	manip.	dist.	meas.	Unmeas.	Control	
$M_T$						✓
$M_E$						✓
$M_Y$						✓
$M_W$						✓
$S$				✓		
$E$				✓		
$Y$				✓		

b) Assumptions:

1.) ideal mixing conditions.

2.) Net change in the density & volume of the solution is negligible.

3.) No initial mass of ethanol or yeast i.e.,  $E_0 = 0$  &  $Y_0 = 0$

Substrate balance.  $\overset{0}{\text{flow in}} - \overset{0}{\text{flow out}} + \overset{0}{\text{generation}} - \text{consumption}$ .  
 accumulation =

$$\frac{dSM_T}{dt} = -\mu SM_T \quad \text{where } SM_T = M_S$$

$$\Rightarrow \frac{dS}{dt} = -\frac{\mu_{\max} S}{K_m + S} \quad \text{--- (1)}$$

From mass balance, we also know that mass of substrate consumed = mass of yeast and ethanol produced:

$$\text{i.e., } \underbrace{S_0 M_T - SM_T}_{\text{mass of substrate consumed}} = \underbrace{EM_T}_{\text{mass of ethanol produced}} + \underbrace{YM_T}_{\text{mass of yeast produced}} \quad \text{--- (2)}$$

$$\text{Also: } EM_T = YM_T \quad \text{(given)} \quad \text{--- (3)}$$

$\therefore$  Substituting (3) into (2) yields:

$$\begin{aligned} S_0 M_T - SM_T &= 2EM_T \\ \Rightarrow \frac{S_0 - S}{2} &= E = Y \quad \text{--- (4)} \end{aligned}$$

differentiating (4) w.r.t. 't':

$$\frac{dE}{dt} = \frac{-dS}{2dt} = \frac{1}{2} \frac{\mu_{\max} S}{K_m + S} \quad \text{--- (5)}$$

$$\text{Similarly, } \frac{dY}{dt} = \frac{1}{2} \frac{\mu_{\max} S}{K_m + S} \quad \text{--- (6)}$$

finally, the dynamic model of the system is given as

$$\frac{dS}{dt} = -\frac{\mu_{\max} S}{K_m + S}$$

$$\frac{dE}{dt} = \frac{1}{2} \frac{\mu_{\max} S}{K_m + S}$$

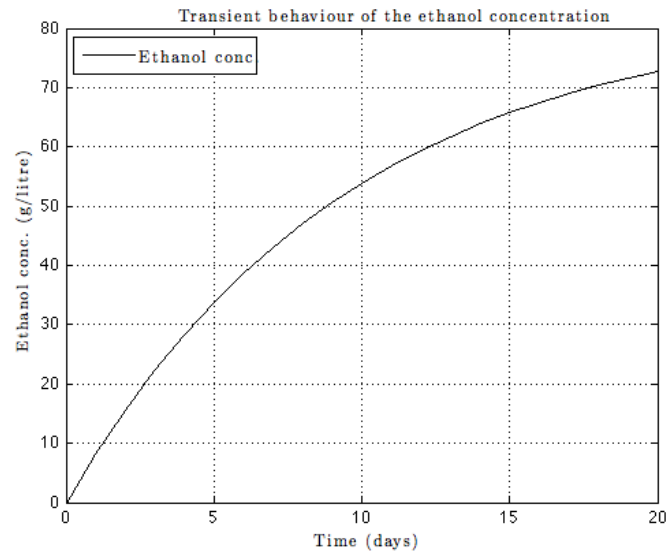
$$\frac{dY}{dt} = \frac{1}{2} \frac{\mu_{\max} S}{K_m + S}$$

- d) The above model is non-linear w.r.t the variable 's'.
- e) Refer to Fig. 1.
- f) Refer to Fig 2.
- g) liquid level 'h' in the kettle doesn't depend on the length of time. See Assumption (2)

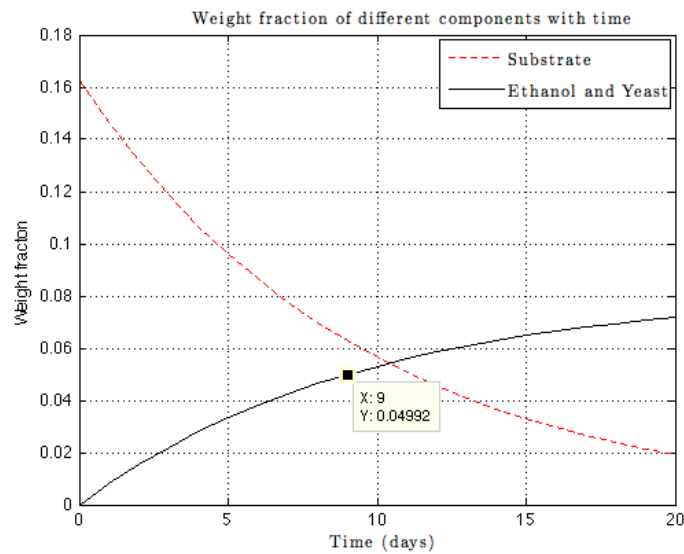
### Appendix

- $V_T = 20$  litres (See Assumption (2))
- $M_T = \underbrace{17 \times 1000}_{\text{mass of water}} + \underbrace{3200}_{\text{mass of malt}} + \underbrace{100}_{\text{mass of hops}} = 20300$  grams
- $S_0 = \frac{3200 + 100}{M_T} = \frac{3300}{20300} = 0.1626$
- $E_0 = 0$
- $Y_0 = 0$  } (See Assumption 3)
- $K_m = 5$
- $\mu_{\max} = 0.54 \text{ day}^{-1}$

e)



f)

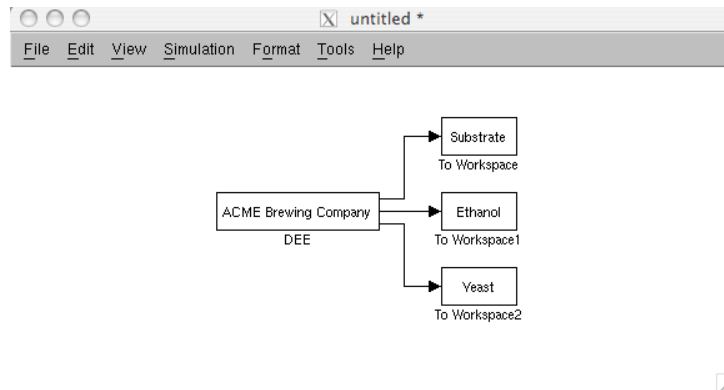


A batch of beer with 5wt% ethanol content takes approximately 9 days of brewing time.

Mixture composition at the end of a batch:

Ethanol=	5%	(see the DataTip on the graph)
Yeast=	5%	(since Ethanol production=Yeast production)
Substrate=	6.27%	(Also from the graph)
Water=	83.33%	





SIMULINK sheet

untitled/DEE

Differential Equation Editor (Fcn block syntax)

Name:

# of inputs:

First order equations, f(x,u):		x0
dx/dt	-0.54*x(1)/(5+x(1))	0.1626
	1/2*0.54*x(1)/(5+x(1))	0
	1/2*0.54*x(1)/(5+x(1))	0

Number of states = 3      Total = 3

Output Equations, f(x,u):

y =

x(1)
x(2)
x(3)

Help    Rebuild    Undo    Done

Status: READY

System model with initial conditions