

Supplementary material for On the minimax robustness against correlation and heteroscedasticity of ordinary least squares among generalized least squares estimates of regression

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1. DETAILS RELATED TO REMARK 1

We take $\Phi(\Sigma) = \det(\Sigma)$ and consider the ratio $r(X, C_0)$ of the maximum loss of the GLS estimate to that of the OLS estimate. This is

$$r(X, C_0) = \frac{\max_{C_M} \mathcal{L}(C | P_0)}{\max_{C_M} \mathcal{L}(C | I_n)} = \frac{\mathcal{L}(\eta^2 I_n | P_0)}{\mathcal{L}(\eta^2 I_n | I_n)} = \frac{|X^T C_0^{-2} X| |X^T X|}{|X^T C_0^{-1} X|^2} = \frac{|Q^T C_0^{-2} Q|}{|Q^T C_0^{-1} Q|^2},$$

where the final term employs the QR-decomposition of X . Of course $r(X, C_0) \geq 1$; a direct proof follows from the observation that

$$Q^T C_0^{-2} Q - (Q^T C_0^{-1} Q)^2 = Q^T C_0^{-1} \{I_n - Q Q^T\} C_0^{-1} Q \succeq 0.$$

For the equicorrelation model with $\rho > 0$ and $C_0 = (1 - \rho)(I_n + \alpha 1_n 1_n^T)$ for $\alpha = \rho / (1 - \rho) \in (0, \infty)$, we calculate that

$$\begin{aligned} C_0^{-1} &= (1 - \rho)^{-1} (I_n - \beta 1_n 1_n^T) \text{ for } \beta = \alpha / (1 + n\alpha) \in (0, n^{-1}), \\ C_0^{-2} &= (1 - \rho)^{-2} (I_n - \gamma 1_n 1_n^T) \text{ for } \gamma = 2\beta - n\beta^2 \in (0, n^{-1}), \end{aligned}$$

and then $r(X, C_0) = 1 + (S\beta^2(n - S) / (1 - S\beta)^2)$, for $S = 1_n^T Q Q^T 1_n \in [0, n]$.

For $0 < \varepsilon < n^{-1}$ suppose that ρ is sufficiently large that $\beta = n^{-1} - \varepsilon$, and that $S = n - \varepsilon$. Then

$$r(X, C_0) = 1 + \frac{\phi_n(\varepsilon)}{\varepsilon} \text{ for } \phi_n(\varepsilon) = \frac{(n - \varepsilon)(n^{-1} - \varepsilon)^2}{(n + n^{-1} - \varepsilon)^2} > 0,$$

and $r(X, C_0) \rightarrow \infty$ as $\varepsilon \rightarrow 0$ and $\phi_n(\varepsilon) \rightarrow 1 / (1 + n^2)$.

A simple example in which $S = n - \varepsilon$ is attained has $p = 1$, $X = x_{n \times 1}$. Then $Q = x / \|x\|$ and, with $\sigma_X^2 = (\sum x^2 - n\bar{x}^2) / n$, we have $S = n\bar{x}^2 / (\sigma_X^2 + \bar{x}^2)$. Then $S = n - \varepsilon$ if the x_i are sufficiently concentrated that $\sigma_X^2 = \varepsilon\bar{x}^2 / (n - \varepsilon)$. This example extends easily to arbitrary p .

2. THEORETICAL COMPLEMENTS FOR §4

PROOF OF THEOREM 1. Recall the constraints O and B:

$$\sum_{x \in \mathcal{X}} f(x) \psi(x) = 0_{p \times 1}, \quad (\text{S.1a})$$

$$\sum_{x \in \mathcal{X}} \psi^2(x) \leq \tau^2. \quad (\text{S.1b})$$

Using (S.1a), the IMSPE $\sum_{x \in \mathcal{X}} E[f^T(x) \hat{\theta} - E\{Y(x)\}]^2$ decomposes as

$$\mathcal{I}(\xi, P | \psi, C) = \sum_{x \in \mathcal{X}} f^T(x) \text{cov}(\hat{\theta} | C, P) f(x) + \sum_{x \in \mathcal{X}} f^T(x) b_{\psi, P} b_{\psi, P}^T f(x) + \sum_{x \in \mathcal{X}} \psi^2(x).$$

Here $b_{\psi, P} = E(\hat{\theta}) - \theta_0$ is the bias. Denote by ψ_X the $n \times 1$ vector consisting of the values of ψ corresponding to the rows of X , so that $b_{\psi, P} = (X^T P X)^{-1} X^T P \psi_X$. Recall that $X = JF$; note as well that $\psi_X = J\bar{\psi}$ for $\bar{\psi} = (\psi(x_1), \dots, \psi(x_N))^T$. Then the above becomes

$$\begin{aligned} \mathcal{I}(\xi, P | \psi, C) &= \text{tr} \left\{ F \text{cov}(\hat{\theta} | C, P) F^T \right\} \\ &+ \bar{\psi}^T J^T P J F (F^T J^T P J F)^{-1} F^T F (F^T J^T P J F)^{-1} F^T J^T P J \bar{\psi} + \bar{\psi}^T \bar{\psi}. \end{aligned} \quad (\text{S.2})$$

As in §3, and taking $K = F^T F$ in (iv) of that section, for $C \in \mathcal{C}_M$ the trace in (S.2) is maximized by $C = \eta^2 I_n$, with

$$\text{tr} \left\{ F \text{cov}(\hat{\theta} | \eta^2 I_n, P) F^T \right\} = \eta^2 \text{tr} \left\{ F (F^T J^T P J F)^{-1} (F^T J^T P^2 J F) (F^T J^T P J F)^{-1} F^T \right\}. \quad (\text{S.3})$$

Extend the orthogonal basis for $\text{col}(F)$ – formed by the columns of Q – by appending to Q the matrix $Q_* : N \times (N - p)$, whose columns form an orthogonal basis for the orthogonal complement $\text{col}(F)^\perp$. Then $(Q; Q_*) : N \times N$ is an orthogonal matrix and we have that $F = QR$ for a non-singular R . If the construction is carried out by the Gram-Schmidt method, then R is upper triangular.

Constraint (S.1a) dictates that $\bar{\psi}$ lie in $\text{col}(Q_*)$. A maximizing ψ will satisfy the bound in constraint (S.1b) with equality, hence $\bar{\psi} = \tau Q_* \beta$ for some $\beta_{(N-p) \times 1}$ with unit norm. Combining these observations along with (S.2) and (S.3) yields that $\max_{\psi, C} \mathcal{I}(\xi, P | \psi, C)$ is given by

$$\begin{aligned} &\eta^2 \text{tr} \left\{ Q (Q^T U Q)^{-1} (Q^T V Q) (Q^T U Q)^{-1} Q^T \right\} \\ &+ \tau^2 \max_{\|\beta\|=1} \left\{ \beta^T Q_*^T U Q (Q^T U Q)^{-1} Q^T Q (Q^T U Q)^{-1} Q^T U Q_* \beta + 1 \right\}. \end{aligned} \quad (\text{S.4})$$

Here and below we use that $\text{tr} AB = \text{tr} BA$, and that such products have the same non-zero eigenvalues. Then (S.4) becomes $(\tau^2 + \eta^2)$ times $\mathcal{I}_\nu(\xi, P)$, given by

$$\begin{aligned} \mathcal{I}_\nu(\xi, P) &= (1 - \nu) \text{tr} \left\{ (Q^T U Q)^{-1} (Q^T V Q) (Q^T U Q)^{-1} \right\} \\ &+ \nu \left\{ \text{ch}_{\max} Q_*^T U Q (Q^T U Q)^{-1} \cdot (Q^T U Q)^{-1} Q^T U Q_* + 1 \right\}. \end{aligned} \quad (\text{S.5})$$

The maximum eigenvalue (denoted above by ch_{\max}) is also that of

$$\begin{aligned} (Q^T U Q)^{-1} Q^T U Q_* \cdot Q_*^T U Q (Q^T U Q)^{-1} &= (Q^T U Q)^{-1} Q^T U (I_N - Q Q^T) U Q (Q^T U Q)^{-1} \\ &= (Q^T U Q)^{-1} Q^T U^2 Q (Q^T U Q)^{-1} - I_p; \end{aligned}$$

this in (S.5) gives (4) of Theorem 1. \square

Theorem 2 below is used show that the experimenter can often design in such a way that $P = I_n$ is a minimax precision matrix, so that OLS is a minimax procedure. In particular, this holds if the design is uniform on its support. This is Remark 3 of the main article.

Recall the class \mathcal{J} of indicator matrices. For $J \in \mathcal{J}$ let $J_+ : n \times q$ be the result of retaining only the non-zero columns of J , so that $JJ^T = J_+J_+^T$, and $D_+ = J_+^T J_+$ is the diagonal matrix containing the positive n_i . If the columns removed have labels j_1, \dots, j_{N-q} then let $Q_+ : q \times p$ be the result of removing these rows from Q , so that $JQ = J_+Q_+$ and $Q^T DQ = Q_+^T D_+ Q_+$. Now define $\alpha = n/\text{tr}(D_+^{-1})$ and

$$P_0 = \alpha J_+ D_+^{-2} J_+^T, \quad (\text{S.6})$$

with $\text{tr} P_0 = n$. Note that

$$\text{rk}(P_0) = \text{rk}(J_+ D_+^{-1}) = \text{rk}(D_+^{-1} J_+^T J_+ D_+^{-1}) = \text{rk}(D_+^{-1}) = q,$$

so that P_0 is positive definite iff $q = n$. This is relevant in part (ii) of Theorem 2, where we deal with the possible rank deficiency of P_0 by introducing

$$P_\varepsilon = (P_0 + \varepsilon I_n) / (1 + \varepsilon); \quad (\text{S.7})$$

for $\varepsilon > 0$, P_ε is positive definite with $\text{tr}(P_\varepsilon) = n$.

THEOREM 2. (i) Suppose that $q \leq N$ and the design is uniform on q points of χ , with $k \geq 1$ observations at each x_i . Then $n = kq$, $D_+ = kI_q$, and $P = I_n$ is a minimax precision matrix:

$$\mathcal{I}_\nu(\xi, I_n) = \min_{P \succ 0} \mathcal{I}_\nu(\xi, P); \quad (\text{S.8})$$

thus OLS is minimax within the class of GLS methods. In particular this holds if $P_0 = I_n$, where P_0 is defined at (S.6).

(ii) Suppose that a design ξ places mass on $q \leq N$ points of χ , that $P_0 \neq I_n$, and that neither of the following holds:

$$(Q_+^T Q_+)^{-1} (Q_+^T D_+^{-1} Q_+) (Q_+^T Q_+)^{-1} = (Q_+^T D_+ Q_+)^{-1}, \quad (\text{S.9a})$$

$$ch_{\max} \left\{ (Q_+^T D_+ Q_+)^{-1} (Q_+^T D_+^2 Q_+) (Q_+^T D_+ Q_+)^{-1} \right\} = ch_{\max} \left\{ (Q_+^T Q_+)^{-1} \right\}. \quad (\text{S.9b})$$

Then in particular D_+ is not a multiple of I_q and so the design is non-uniform. With P_ε as defined at (S.7), there is $\nu_0 \in (0, 1)$ for which, for each $\nu \in (\nu_0, 1]$, $\mathcal{I}_\nu(\xi, P_\varepsilon) < \mathcal{I}_\nu(\xi, I_n)$. Thus OLS is not minimax for such (ξ, ν) .

Remark 4. The requirement of Theorem 2(ii) that (S.9a) and (S.9b) fail excludes more designs than those which are uniform on their supports, and is a condition on Q as well as on the design. For instance if $Q_+ (Q_+^T Q_+)^{-1/2} = A_{q \times p}$ is block-diagonal: $A = \oplus_{i=1}^m A_i$, where $A_i : q_i \times p_i$ ($\sum q_i = q$, $\sum p_i = p$) satisfies $A_i^T A_i = I_{p_i}$, and if $D_+ = \oplus_{i=1}^m k_i I_{q_i}$, then

$$A^T D_+^{-1} A = (A^T D_+ A)^{-1}, \quad (\text{S.10})$$

$$(A^T D_+ A)^{-1} A^T D_+^2 A (A^T D_+ A)^{-1} = I_p. \quad (\text{S.11})$$

Equation (S.10) gives (S.9a), and (S.11) asserts the equality of the two matrices in (S.9b), hence of their maximum eigenvalues. These equations are satisfied even though the design is non-uniform if the k_i are not all equal.

The proof of Theorem 2 follows that of the following preliminary result.

LEMMA 2. (i) For a fixed design ξ and any $P \succ 0$, $\mathcal{I}_0(\xi, P) \geq \mathcal{I}_0(\xi, I_n)$ and $\mathcal{I}_1(\xi, P) \geq \text{ch}_{\max} \left\{ (Q_+^T Q_+)^{-1} \right\}$.

If neither of the equations (S.9a), (S.9b) holds, then:

(ii) $\mathcal{I}_0(\xi, P_0) > \mathcal{I}_0(\xi, I_n)$ and $\mathcal{I}_1(\xi, I_n) > \mathcal{I}_1(\xi, P_0)$;

(iii) With P_ε as defined in Theorem 2(ii), and for sufficiently small $\varepsilon > 0$, $\Delta_0(\varepsilon) = \mathcal{I}_0(\xi, P_\varepsilon) - \mathcal{I}_0(\xi, I_n) > 0$ and $\Delta_1(\varepsilon) = \mathcal{I}_1(\xi, I_n) - \mathcal{I}_1(\xi, P_\varepsilon) > 0$.

PROOF OF LEMMA 2.

(i) From (4a), $\mathcal{I}_0(\xi, P) - \mathcal{I}_0(\xi, I_n)$ is the trace of

$$\begin{aligned} & (Q^T J^T P J Q)^{-1} (Q^T J^T P^2 J Q) (Q^T J^T P J Q)^{-1} - (Q^T J^T J Q)^{-1} \\ &= (Q^T J^T P J Q)^{-1} Q^T J^T P \left\{ I_n - J Q (Q^T J^T J Q)^{-1} Q^T J^T \right\} P J Q (Q^T J^T P J Q)^{-1}, \end{aligned}$$

which is $\succeq 0$ with non-negative trace. For the second inequality first note that

$$\begin{aligned} & (Q^T U Q)^{-1} Q^T U^2 Q (Q^T U Q)^{-1} - (Q_+^T Q_+)^{-1} \\ &= (Q_+^T J_+^T P J_+ Q_+)^{-1} Q_+^T J_+^T P J_+ J_+^T P J_+ Q_+ (Q_+^T J_+^T P J_+ Q_+)^{-1} - (Q_+^T Q_+)^{-1} \\ &= (Q_+^T J_+^T P J_+ Q_+)^{-1} Q_+^T J_+^T P J_+ \left\{ I_n - Q_+ (Q_+^T Q_+)^{-1} Q_+^T \right\} J_+^T P J_+ Q_+ (Q_+^T J_+^T P J_+ Q_+)^{-1} \end{aligned}$$

is p.s.d., so that by Weyl's Monotonicity Theorem (p. 63 of Bhatia (1997)),

$$\mathcal{I}_1(\xi, P) = \text{ch}_{\max} \left\{ (Q^T U Q)^{-1} Q^T U^2 Q (Q^T U Q)^{-1} \right\} \geq \text{ch}_{\max} \left\{ (Q_+^T Q_+)^{-1} \right\}.$$

(ii) We use the following identities, which follow from (4a) and (4b):

$$\mathcal{I}_0(\xi, I_n) = \text{tr} \left\{ (Q_+^T D_+ Q_+)^{-1} \right\} \quad (\text{S.12a})$$

$$\mathcal{I}_1(\xi, I_n) = \text{ch}_{\max} \left\{ (Q_+^T D_+ Q_+)^{-1} (Q_+^T D_+^2 Q_+) (Q_+^T D_+ Q_+)^{-1} \right\} \quad (\text{S.12b})$$

$$\mathcal{I}_0(\xi, P_0) = \text{tr} \left\{ (Q_+^T Q_+)^{-1} (Q_+^T D_+^{-1} Q_+) (Q_+^T Q_+)^{-1} \right\}, \quad (\text{S.12c})$$

$$\mathcal{I}_1(\xi, P_0) = \text{ch}_{\max} \left\{ (Q_+^T Q_+)^{-1} \right\}. \quad (\text{S.12d})$$

To prove (ii) we show that if either inequality fails then one of (S.9a), (S.9b) holds – a contradiction. First note that

$$\begin{aligned} & \mathcal{I}_0(\xi, P_0) - \mathcal{I}_0(\xi, I_n) \\ &= \text{tr} \left\{ (Q_+^T Q_+)^{-1} (Q_+^T D_+^{-1} Q_+) (Q_+^T Q_+)^{-1} - (Q_+^T D_+ Q_+)^{-1} \right\} \\ &= \text{tr} \left\{ (Q_+^T Q_+)^{-1} Q_+^T D_+^{-1/2} \left[I_q - D_+^{1/2} Q_+ (Q_+^T D_+ Q_+)^{-1} Q_+^T D_+^{1/2} \right] D_+^{-1/2} Q_+ (Q_+^T Q_+)^{-1} \right\}, \end{aligned} \quad (\text{S.13})$$

which is non-negative. If the first inequality fails, so that $\mathcal{I}_0(\xi, P_0) = \mathcal{I}_0(\xi, I_n)$, then the trace of the p.s.d. matrix at (S.13) is zero, hence all eigenvalues are zero and the matrix is the zero matrix. This is (S.9a).

That $\mathcal{I}_1(\xi, I_n) - \mathcal{I}_1(\xi, P_0) \geq 0$ is the first inequality in (i). If the second inequality of (ii) fails, then $\mathcal{I}_1(\xi, I_n) = \mathcal{I}_1(\xi, P_0)$ and their evaluations at (S.12b) and (S.12d) give (S.9b).

For (iii), that $\Delta_0(\varepsilon) > 0$ and $\Delta_1(\varepsilon) > 0$ for sufficiently small ε follow from the continuity of $\mathcal{I}_0(\xi, P_\varepsilon)$ and $\mathcal{I}_1(\xi, P_\varepsilon)$ as functions of ε : $\Delta_0(\varepsilon) \rightarrow \mathcal{I}_0(\xi, P_0) - \mathcal{I}_0(\xi, I_n) > 0$ and $\Delta_1(\varepsilon) = \mathcal{I}_1(\xi, I_n) - \mathcal{I}_1(\xi, P_0) > 0$ as $\varepsilon \rightarrow 0$. \square

PROOF OF THEOREM 2.

(i) From the first inequality in Lemma 2 (i),

$$\mathcal{I}_0(\xi, I_n) = \min_{P \succ 0} \mathcal{I}_0(\xi, P).$$

If $P = I_n$ then $U = J^T P J = J^T J = D_+ = kI_q$, so that from (S.12b), and the second inequality in Lemma 2(i),

$$\mathcal{I}_1(\xi, I_n) = \text{ch}_{\max} \left\{ (Q_+^T Q_+)^{-1} \right\} = \min_{P \succ 0} \mathcal{I}_1(\xi, P).$$

Now (S.8) is immediate. If $P_0 = I_n$ then $q = \text{rk}(P_0) = n$, so that all n observations are made at distinct points, hence $D_+ = I_n$ and the design is uniform on its support.

(ii) By Lemma 2(iii) there is $\varepsilon_0 > 0$ for which $\Delta_0(\varepsilon) > 0$ and $\Delta_1(\varepsilon) > 0$ when $0 < \varepsilon \leq \varepsilon_0$. For ε in this range,

$$\mathcal{I}_\nu(\xi, I_n) - \mathcal{I}_\nu(\xi, P_\varepsilon) = \nu(\Delta_0(\varepsilon) + \Delta_1(\varepsilon)) - \Delta_0(\varepsilon) > 0,$$

for $\nu \in (\nu_0, 1]$ and $\nu_0 \equiv \Delta_0(\varepsilon) / (\Delta_0(\varepsilon) + \Delta_1(\varepsilon))$. □

3. TABLES OF SIMULATION RESULTS

Table 1. Minimax precision matrices; multinomial designs:
means of performance measures ± 1 standard error.

Response	N	ν	$\%I_n$	$\mathcal{I}_\nu(\xi, I_n)$	$\mathcal{I}_\nu(\xi, P^\nu)$	$T_1(\%)$	$T_2(\%)$	$T_3(\%)$
linear $n = 10$	11	.5	1	$3.34 \pm .11$	$3.19 \pm .11$	$4.16 \pm .15$	$3.23 \pm .12$	$12.29 \pm .46$
	11	1	1	$3.72 \pm .16$	$3.27 \pm .14$	$11.81 \pm .35$	$9.18 \pm .31$	$14.40 \pm .52$
	51	.5	27	$11.19 \pm .21$	$11.05 \pm .21$	$1.24 \pm .07$	$.85 \pm .05$	$4.10 \pm .22$
	51	1	27	$9.80 \pm .23$	$9.35 \pm .22$	$4.34 \pm .22$	$2.96 \pm .16$	$4.82 \pm .26$
quadratic $n = 15$	11	.5	0	5.99 ± 1.25	5.57 ± 1.06	$4.62 \pm .15$	$3.15 \pm .11$	$14.16 \pm .50$
	11	1	0	7.30 ± 1.82	6.07 ± 1.27	$13.04 \pm .38$	$8.57 \pm .38$	$16.22 \pm .57$
	51	.5	4	$12.61 \pm .46$	$12.40 \pm .45$	$1.58 \pm .07$	$.99 \pm .05$	$5.75 \pm .27$
	51	1	4	$10.69 \pm .54$	$10.03 \pm .51$	$5.95 \pm .24$	$3.54 \pm .17$	$6.72 \pm .31$
cubic $n = 20$	11	.5	0	9.71 ± 1.63	9.15 ± 1.52	$4.87 \pm .15$	$3.25 \pm .11$	$14.90 \pm .51$
	11	1	0	12.98 ± 2.53	11.41 ± 2.22	$13.54 \pm .38$	$8.86 \pm .29$	$16.92 \pm .58$
	51	.5	0	21.67 ± 2.43	21.21 ± 2.38	$1.87 \pm .08$	$1.14 \pm .05$	$7.24 \pm .30$
	51	1	0	20.76 ± 2.9	19.29 ± 2.81	$7.39 \pm .26$	$3.75 \pm .16$	$8.45 \pm .35$

Table 2. Minimax precision matrices; symmetrized designs:
means of performance measures ± 1 standard error.

Response	N	ν	$\%I_n$	$\mathcal{I}_\nu(\xi, I_n)$	$\mathcal{I}_\nu(\xi, P^\nu)$	$T_1(\%)$	$T_2(\%)$	$T_3(\%)$
linear $n = 10$	11	.5	20	$2.10 \pm .03$	$2.05 \pm .03$	$2.45 \pm .11$	$1.64 \pm .07$	$8.46 \pm .41$
	11	1	20	$1.83 \pm .04$	$1.66 \pm .04$	$8.51 \pm .31$	$4.99 \pm .21$	$10.06 \pm .46$
	51	.5	80	$10.01 \pm .29$	$9.97 \pm .29$	$.40 \pm .05$	$.23 \pm .03$	$1.45 \pm .18$
	51	1	80	$7.77 \pm .29$	$7.67 \pm .29$	$1.48 \pm .16$	$.67 \pm .07$	$1.66 \pm .20$
quadratic $n = 15$	11	.5	0	$2.35 \pm .08$	$2.26 \pm .07$	$3.49 \pm .07$	$2.17 \pm .07$	$14.10 \pm .50$
	11	1	0	$2.01 \pm .09$	$1.74 \pm .08$	$14.40 \pm .37$	$8.57 \pm .22$	$18.05 \pm .58$
	51	.5	85	$10.58 \pm .70$	$10.53 \pm .68$	$.25 \pm .04$	$.15 \pm .02$	$1.02 \pm .16$
	51	1	85	$7.54 \pm .80$	$7.39 \pm .74$	$1.03 \pm .15$	$.49 \pm .07$	$1.19 \pm .19$
cubic $n = 20$	11	.5	3	$2.64 \pm .19$	$2.55 \pm .19$	$3.56 \pm .12$	$1.99 \pm .07$	$15.18 \pm .56$
	11	1	3	$2.39 \pm .27$	$2.11 \pm .26$	$15.19 \pm .44$	$9.09 \pm .28$	$19.69 \pm .70$
	51	.5	58	11.97 ± 1.91	11.80 ± 1.80	$.45 \pm .04$	$.24 \pm .02$	$2.11 \pm .19$
	51	1	58	8.44 ± 2.14	7.94 ± 1.80	$2.23 \pm .18$	$.86 \pm .07$	$2.47 \pm .21$

In Tables 1 and 2, uniform designs account for 100% and 95%, respectively, of the cases in which $P^\nu = I_n$ is optimal. Common exceptions in Table 2 are designs which are uniform apart from having points added or removed at $x = 0$ to maintain symmetry. Those designs for which I_n is not optimal all meet the conditions of Theorem 2 (ii). This was checked numerically: since (S.9a) implies that $\mathcal{I}_0(\xi, P_0) - \mathcal{I}_0(\xi, I_n) = 0$, and (S.9b) implies that $\mathcal{I}_1(\xi, I_n) - \mathcal{I}_1(\xi, P_0) = 0$, their failure is verified by checking that each of these differences is positive.

Table 3. Minimax designs and precision matrices:
performance measures ($T_1 = T_2 = T_3 = 0$ if $P^\nu = I_n$).

Response	N	ν	$\mathcal{I}_\nu(\xi, I_n)$	$\mathcal{I}_\nu(\xi, P^\nu)$	$T_1(\%)$	$T_2(\%)$	$T_3(\%)$
linear $n = 10$	11	.5	1.60	1.60	0	0	0
	11	1	1.10	1.10	0	0	0
	51	.5	6.14	6.14	0	0	0
	51	1	5.10	5.10	0	0	0
quadratic $n = 15$	11	.5	1.61	1.53	4.67	2.81	16.06
	11	1	1.12	1.00	10.84	10.78	10.84
	51	.5	5.80	5.80	0	0	0
	51	1	3.40	3.40	0	0	0
cubic $n = 20$	11	.5	1.55	1.53	1.46	1.13	6.04
	11	1	1.12	1.00	11.03	4.84	11.03
	51	.5	5.56	5.56	0	0	0
	51	1	2.55	2.55	0	0	0

REFERENCES

BHATIA, R. (1997). *Matrix Analysis*. Berlin: Springer.